

Package ‘mmand’

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Author Jon Clayden

Maintainer Jon Clayden <code@clayden.org>

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Description This package provides tools for performing mathematical morphology operations, such as erosion and dilation, on data of arbitrary dimensionality. It can also be used for re-sampling, filtering, smoothing and other image processing-style operations.

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binarise	<i>Binarise a numeric array</i>
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Description

This function binarises an array, setting all nonzero elements to unity.

Usage

```
binarise(x)
```

Arguments

x An object that can be coerced to an array, or for which a [morph](#) method exists.

Value

A morphed array with the same dimensions as the original array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[morph](#) for the function underlying this operation, and [erode](#) for mathematical morphology functions.

binary	<i>Check for a binary array</i>
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Description

This function checks whether a numeric array is binary, with only one unique nonzero value, or not.

Usage

```
binary(x)
```

Arguments

x An object that can be coerced to a numeric array

Value

A logical value indicating whether the array is binary or not. Binary in this case means that the array contains only one unique nonzero value.

Author(s)

Jon Clayden <code@clayden.org>

display	<i>Display a 2D image</i>
---------	---------------------------

Description

This function displays a 2D greyscale image. It is a wrapper around `image`, with more sensible defaults for images. It is (S3) generic.

Usage

```
display(x, ...)
```

```
## Default S3 method:
```

```
display(x, transpose = TRUE, useRaster = TRUE, add = FALSE, ...)
```

Arguments

<code>x</code>	An object that can be coerced to a numeric matrix.
<code>transpose</code>	Whether to transpose the matrix before display. This is usually necessary due to the conventions of <code>image</code> .
<code>useRaster</code>	Whether to use raster graphics if possible. This is generally preferred for speed. Passed to <code>image</code> .
<code>add</code>	Whether to add the image to an existing plot.
<code>...</code>	Additional arguments to <code>image</code> .

Details

Relative to the defaults for `image` (from the `graphics` package), this function transposes and then inverts the matrix along the y-direction, uses a grey colour scale, fills the entire device with the image, and tries to size the image correctly given the dot pitch of the display. Unfortunately the latter is not always possible, due to downstream limitations.

Value

This function is called for its side-effect of displaying an image on a new R device.

Author(s)

Jon Clayden <code@clayden.org>

filters	<i>Apply a filter to an array</i>
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Description

These functions apply mean or median filters to an array.

Usage

```
medianFilter(x, kernel)
meanFilter(x, kernel)
```

Arguments

x	An object that can be coerced to an array, or for which a morph method exists.
kernel	A kernel array, indicating the scope of the filter.

Value

A morphed array with the same dimensions as the original array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[morph](#) for the function underlying this operation, and [kernels](#) for kernel-generating functions.

gameOfLife	<i>Conway's Game of Life</i>
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Description

An implementation of Conway's Game of Life, a classical cellular automaton, using the [morph](#) function. The [gospersGliderGun](#) function provides an interesting starting configuration.

Usage

```
gameOfLife(init, size, density = 0.3, steps = 200, viz = FALSE, tick = 0.5)
gospersGliderGun()
```

Arguments

<code>init</code>	The initial state of the automaton, a binary matrix. If missing, the initial state will be randomly generated, with a population density given by <code>density</code> .
<code>size</code>	The dimensions of the board. Defaults to the size of <code>init</code> , but must be given if that parameter is missing. If both are specified and <code>size</code> is larger than the dimensions of <code>init</code> , then the latter will be padded with zeroes.
<code>density</code>	The approximate population density of the starting state. Ignored if <code>init</code> is provided.
<code>steps</code>	The number of generations of the automaton to simulate.
<code>viz</code>	If TRUE, the state of the system at each generation is plotted.
<code>tick</code>	The amount of time, in seconds, to pause before plotting each successive generation. Ignored if <code>viz</code> is FALSE.

Details

Conway's Game of Life is a simple cellular automaton, based on a 2D matrix of "cells". It shows complex behaviour based on four simple rules. These are:

1. Any live cell with fewer than two live neighbours dies, as if caused by under-population.
2. Any live cell with two or three live neighbours lives on to the next generation.
3. Any live cell with more than three live neighbours dies, as if by overcrowding.
4. Any dead cell with exactly three live neighbours becomes a live cell, as if by reproduction.

Live and dead cells are represented by 1s and 0s in the matrix, respectively.

The initial state and the rules above completely determine the behaviour of the system. The Gosper glider gun is an interesting starting configuration that generates so-called "gliders", which propagate across the board.

In principle the size of the board in a cellular automaton is infinite. Of course this is not easy to simulate, but this implementation adds a border of two extra cells around the board on all sides to approximate an infinite board slightly better. These are not visualised, nor returned in the final state.

Value

A binary matrix representing the final state of the system after `steps` generations.

Author(s)

Jon Clayden <code@clayden.org>

See Also

The [morph](#) function, which powers this simulation.

Examples

```
## Not run: gameOfLife(init=gosperGliderGun(), size=c(40,40), steps=50, viz=TRUE)
```

gaussianSmooth	<i>Smooth a numeric array with a Gaussian kernel</i>
----------------	--

Description

This function smooths an array using a Gaussian kernel with a specified standard deviation.

Usage

```
gaussianSmooth(x, sigma)
```

Arguments

x	An object that can be coerced to an array, or for which a morph method exists.
sigma	A numeric vector giving the standard deviation of the kernel in each dimension. Can have lower dimensionality than the target array.

Value

A morphed array with the same dimensions as the original array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[morph](#) for the function underlying this operation, [gaussianKernel](#) for generating Gaussian kernels (which is also used by this function), and [erode](#) for mathematical morphology functions.

kernels	<i>Kernel-generating functions</i>
---------	------------------------------------

Description

These functions can be used to generate kernels for morphological, smoothing or resampling operations. There are two types of kernels: kernel arrays, which are used with [morph](#), and kernel functions, which are used with [resample](#).

Usage

```

isKernel(object)

kernelArray(values)
isKernelArray(object)

shapeKernel(width, dim = length(width), type = c("box", "disc", "diamond"),
  binary = TRUE, normalised = FALSE)
gaussianKernel(sigma, dim = length(sigma), size = 6*sigma, normalised = TRUE)

kernelFunction(name = c("box", "triangle", "mitchell-netravali"), ...)
isKernelFunction(object)

boxKernel()
triangleKernel()
mitchellNetravaliKernel(B = 1/3, C = 1/3)
mnKernel(B = 1/3, C = 1/3)

```

Arguments

object	Any object.
values	A numeric vector or array, containing the values of the kernel array.
width	A numeric vector giving the width of the shape in each dimension, in array elements. Does not need to be integer-valued, or equal for all dimensions. Will be recycled to length <code>dim</code> if that parameter is also specified.
sigma	A numeric vector giving the standard deviation of the underlying Gaussian distribution in each dimension, in array elements. Does not need to be equal for all dimensions. Will be recycled to length <code>dim</code> if that parameter is also specified.
dim	An integer value giving the dimensionality of the kernel. Defaults to the length of <code>width</code> or <code>sigma</code> .
size	A numeric vector giving the width of the kernel in each dimension, which will be rounded up to the nearest odd integer. Defaults to four times the corresponding <code>sigma</code> value.
type	A string giving the type of shape to produce. In one dimension, these shapes are all equivalent.
binary	If FALSE, the value of the kernel at each point represents the proportion of the array element within the shape. If TRUE, these values are binarised to be 1 if at least half of the element is within the shape, and 0 otherwise.
normalised	If TRUE, the sum of non-missing elements of the kernel will be unity. Note that this is the default for <code>gaussianKernel</code> , but not for <code>shapeKernel</code> .
name	A string giving the name of the kernel function required.
...	Parameters for the kernel function.
B, C	Mitchell-Netravali coefficients, each of which must be between 0 and 1.

Details

There are two forms of kernel used by this package. Kernel arrays, otherwise known in mathematical morphology as structuring elements, are numeric arrays with class `kernelArray`. They are defined on a grid of odd width, and are used by [morph](#) and related functions. Kernel functions, by contrast, are represented in R as a list containing a name and, optionally, some parameters. The real implementation is in C++. They are defined everywhere within the support of the kernel, and are used by [resample](#) and friends. The key distinction is in whether the kernel will always be centred exactly on the location of an existing value in the data (for kernel arrays) or not (for kernel functions).

The `kernelArray` and `kernelFunction` functions create objects of the corresponding classes, while `isKernelArray` and `isKernelFunction` test for them. In addition, `isKernel` returns TRUE if its argument is of either kernel class.

The remaining functions generate special-case kernels: `shapeKernel` generates arrays with nonzero elements in a box, disc or diamond shape for use with [morphology](#) functions; `gaussianKernel` generates Gaussian coefficients and is used by [gaussianSmooth](#); `boxKernel` is used for “nearest neighbour” resampling, and `triangleKernel` for linear, bilinear, etc. The Mitchell-Netravali kernel, a.k.a. BC-spline, is based on a family of piecewise-cubic polynomial functions, with support of four times the pixel separation in each dimension. The default parameters are the ones recommended by Mitchell and Netravali as a good trade-off between various artefacts, but other well-known special cases include $B=1, C=0$ (the cubic B-spline) and $B=0, C=0.5$ (the Catmull-Rom spline). `mnKernel` is a shorter alias for `mitchellNetravaliKernel`.

Value

For `isKernel`, `isKernelArray` and `isKernelFunction`, a logical value. For `kernelArray`, `shapeKernel` and `gaussianKernel`, a kernel array. For `kernelFunction`, `boxKernel`, `triangleKernel`, `mitchellNetravaliKernel` and `mnKernel`, a kernel function.

Author(s)

Jon Clayden <code@clayden.org>

References

The Mitchell-Netravali kernel is described in the following paper.

D.P. Mitchell & A.N. Netravali (1988). Reconstruction filters in computer graphics. *Computer Graphics* 22(4):221-228.

See Also

[morph](#) for general application of kernel arrays to data, [morphology](#) for mathematical morphology functions, [resample](#) for resampling, and [gaussianSmooth](#) for smoothing. Also see [sampleKernelFunction](#) for kernel sampling and plotting.

Examples

```
shapeKernel(c(3,5), type="diamond")
gaussianKernel(c(0.3,0.3))
mnKernel()
```

morph *Morph an array with a kernel*

Description

The morph function applies a kernel to a target array. Optionally, applying the kernel to a particular array element can be made conditional on its value, or the number of nonzero immediate neighbours that it has. The morph function is (S3) generic.

Usage

```
morph(x, kernel, ...)
```

```
## Default S3 method:
```

```
morph(x, kernel, operator = c("+", "-", "*", "i", "1", "0"),
      merge = c("sum", "min", "max", "mean", "median"), value = NULL,
      valueNot = NULL, nNeighbours = NULL, nNeighboursNot = NULL, ...)
```

Arguments

x	Any object. For the default method, this must be coercible to an array.
kernel	An object representing the kernel to be applied, which must be coercible to an array. It must have odd width in all dimensions, but does not have to be isotropic in size. The kernel's dimensionality may be less than that of the target array, x. See kernel s for kernel-generating functions.
operator	The operator applied elementwise within the kernel, as a function of the original image value and the kernel value. Arithmetic operators are as usual; "i" is the identity operator, where every value within the kernel will be included as-is; and 1 and 0 include a 1 or 0 for each element within the kernel's nonzero region.
merge	The operator applied to combine the elements into a final value for the centre pixel. All have their usual meanings.
value	An optional vector of values in the target array for which to apply the kernel. Takes priority over valueNot if both are specified.
valueNot	An optional vector of values in the target array for which not to apply the kernel.
nNeighbours	An optional numeric vector giving allowable numbers of nonzero neighbours (including diagonal neighbours) for array elements where the kernel will be applied. Takes priority over nNeighboursNot if both are specified.
nNeighboursNot	An optional numeric vector giving nonallowable numbers of nonzero neighbours (including diagonal neighbours) for array elements where the kernel will be applied.
...	Additional arguments to methods.

Value

A morphed array with the same dimensions as the original array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[kernels](#) for kernel-generating functions, and [morphology](#) for more specific mathematical morphology functions. [gameOfLife](#) shows how this function can be used for non-morphological purposes, in that case to power a cellular automaton. See also the `kernel` and `kernapply` functions in the `stats` package, particularly if you want to smooth time series.

morphology

Standard mathematical morphology operations

Description

These functions provide standard mathematical morphology operations, which can be applied to array data with any number of dimensions. Binary and greyscale morphology is supported.

Usage

```
erode(x, kernel)
dilate(x, kernel)
opening(x, kernel)
closing(x, kernel)
```

Arguments

<code>x</code>	An object that can be coerced to an array, or for which a morph method exists.
<code>kernel</code>	An array representing the kernel to be used. See shapeKernel for functions to generate a suitable kernel.

Details

The `erode` function uses the kernel as an eraser, centring it on each zero-valued pixel, which has the effect of eroding the extent of nonzero areas. Dilation has the opposite effect, extending the nonzero regions in the array. Opening is an erosion followed by a dilation, and closing is a dilation followed by an erosion, using the same kernel in both cases.

If the kernel has only one unique nonzero value, it is described as “flat”. For a flat kernel, the erosion is the minimum value of `x` within the nonzero region of kernel. For a nonflat kernel, this becomes minimum value of `x - kernel`. Dilation is the opposite operation, taking the maximum within the kernel.

Value

A morphed array with the same dimensions as the original array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[morph](#) for the function underlying all of these operations, [kernels](#) for kernel-generating functions, [binarise](#) for binarising an array, and [gaussianSmooth](#) for smoothing. The EBImage Bioconductor package also supplies functions to perform these operations, and may be slightly faster, but only works in two dimensions.

Examples

```
x <- c(0,0,1,0,0,0,0,1,1,1,0,0)
k <- c(1,1,1)
erode(x,k)
dilate(x,k)
```

neighbourhood

Get neighbourhood information for an array

Description

This function provides information about the structure of a neighbourhood of a given width within a specified array.

Usage

```
neighbourhood(x, width)
```

Arguments

x	An object that can be coerced to an array.
width	A vector giving the width of the neighbourhood in each dimension, which will be recycled if necessary. Must not be greater than the size of the array. Even values are rounded up to the next odd integer.

Value

A list with the following elements.

widths	The width of the neighbourhood along each dimension. Currently all elements of this vector will be the same.
size	The number of pixels within the neighbourhood.
locs	A matrix giving the coordinates of each neighbourhood pixel, relative to the centre pixel, one per row.
offsets	Vector offsets of the neighbourhood values within x.

Author(s)

Jon Clayden <code@clayden.org>

resample

*Resample an array***Description**

The resample function uses a kernel function to resample a target array. This can be thought of as a generalisation of array indexing which allows fractional indices. It is (S3) generic. The rescale function is an alternative interface for the common case where the image is being scaled to a new size.

Usage

```
resample(x, points, kernel, ...)
```

```
## Default S3 method:
```

```
resample(x, points, kernel, pointType = c("auto", "general", "grid"), ...)
```

```
rescale(x, factor, kernel, ...)
```

Arguments

x	Any object. For the default method, this must be coercible to an array.
points	Either a matrix giving the points to sample at, one per row, or a list giving the locations on each axis, which will be made into a grid.
kernel	A kernel function object, used to provide coefficients for each resampled value, or the name of one.
pointType	A string giving the type of the point specification being used. Usually can be left as "auto".
factor	A vector of scale factors, which will be recycled to the dimensionality of x.
...	Additional options, such as kernel parameters.

Value

If a generalised sampling scheme is used (i.e. with points a matrix), the result is a vector of sampled values. For a grid scheme (i.e. with points a list, including for rescale), it is a resampled array.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[kernels](#) for kernel-generating functions.

Examples

```
resample(c(0,0,1,0,0), seq(0.75,5.25,0.5), triangleKernel())
```

sampleKernelFunction *Sampling and plotting kernels*

Description

These functions can be used to sample and plot kernel profiles.

Usage

```
sampleKernelFunction(kernel, values)
## S3 method for class 'kernelFunction'
plot(x, y, xlim = c(-2,2), lwd = 2, col = "red", ...)
## S3 method for class 'kernelArray'
plot(x, y, axis = 1, lwd = 2, col = "red", ...)
```

Arguments

kernel	A kernel function object.
values	A vector of values to sample the function at. These are in units of pixels, with zero representing the centre of the kernel.
x	A kernel object of the appropriate class.
y	Ignored.
xlim	The limits of the range used to profile the kernel.
lwd	The line width to use for the kernel profile.
col	The line colour to use for the kernel profile.
axis	The axis to profile along.
...	Additional plot parameters.

Value

For `sampleKernelFunction` a vector of kernel values at the locations requested. The plot methods are called for their side-effects.

Author(s)

Jon Clayden <code@clayden.org>

See Also

[kernels](#) for kernel-generating functions.

Examples

```
sampleKernelFunction(mnKernel(), -2:2)  
plot(mnKernel())
```

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