

Package ‘spatialEco’

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Type Package

Title Spatial Analysis and Modeling

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Description Utilities to support spatial data manipulation, query, sampling and modeling. Functions include models for species population density, download utilities for climate and global deforestation spatial products, spatial smoothing, multivariate separability, point process model for creating pseudo-absences and subsampling, polygon and point-distance landscape metrics, auto-logistic model, sampling models, cluster optimization and statistical exploratory tools.

Depends R (>= 3.1.0)

Imports RANN, rms, sp (>= 1.0-15), raster (>= 2.3-10), spatstat (>= 1.35-0), cluster, spdep, SDMTools, RCurl, rgeos

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breeding.density	<i>Breeding density areas</i>
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Description

Calculates breeding density areas base on population counts/density and spatial point density.

Usage

```
breeding.density(x, pop, p = 0.75, bw = 1000, b = 6400, self = TRUE)
```

Arguments

x	sp SpatialPointsDataFrame object
pop	Population count/density coulumn in x@data
p	Target percent of population
bw	Bandwidth distance
b	Buffer distance (eg., p < 0.75 b=6400m, p >= 0.75 b=8500m)
self	Should source observsation be included in neighbor count (TRUE/FALSE)

Value

A list object with:

pop.pts sp point object with points identified within the specified p
 pop.area sp polygon object of buffered points specified by parameter b
 bandwidth Specified distance bandwidth used in identifying neighbor counts
 buffer Specified buffer distance used in buffering points for pop.area
 p Specified population percent

Note

The breeding density areas model identifies the Nth-percent population exhibiting the highest spatial density and counts/frequency. It then buffers these points by a specified distance to produce breeding area polygons.

depends: sp, rgeos

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Doherty, K.E., J.D. Tack, J.S. Evans, D.E. Naugle (2010) Mapping breeding densities of greater sage-grouse: A tool for range-wide conservation planning. Bureau of Land Management. Report Number L10PG00911

Examples

```
require(sp)
n=1500
bb <- rbind(c(-1281299,-761876.5),c(1915337,2566433.5))
bb.mat <- cbind(c(bb[1,1], bb[1,2], bb[1,2], bb[1,1]),
               c(bb[2,1], bb[2,1], bb[2,2], bb[2,2]))
bbp <- Polygon(bb.mat)
s <- spsample(bbp, n, type='random')
pop <- SpatialPointsDataFrame(s, data.frame(ID=1:length(s),
                                           counts=runif(length(s), 1,250)))

bd75 <- breeding.density(pop, pop='counts', p=0.75, b=6400, bw=4000)
plot(bd75$pop.area, main='75% breeding density areas')
plot(pop, pch=20, col='black', add=TRUE)
plot(bd75$pop.pts, pch=20, col='red', add=TRUE)
```

 correlogram

Correlogram

Description

Calculates and plots a correlogram

Usage

```
correlogram(x, v, dist = 5000, dmatrix = FALSE, ns = 99,
            latlong = FALSE, ...)
```

Arguments

x	SpatialPointsDataFrame object
v	Test variable in x@data
dist	Distance of correlation lags, if latlong=TRUE units are in kilometers
dmatrix	Should the distance matrix be include in output (TRUE/FALSE)
ns	Number of simulations to derive simulation envelope
latlong	Coordinates are in latlong (TRUE/FALSE)
...	Arguments passed to cor ('pearson', 'kendall' or 'spearman')

Value

A list object containing:

autocorrelation is a data.frame object with the following components

autocorrelation - Autocorrelation value for each distance lag

dist - Value of distance lag

lci - Lower confidence interval (p=0.025)

uci - Upper confidence interval (p=0.975)

CorrPlot recordedplot object to recall plot

dmatrix Distance matrix (if dmatrix=TRUE)

Note

depends: sp

Author(s)

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Examples

```
library(sp)
data(meuse)
coordinates(meuse) = ~x+y
zinc.cg <- correlogram(x = meuse, v = meuse@data[, 'zinc'], dist = 250, ns = 9)
```

download.daymet	<i>Download DAYMET</i>
-----------------	------------------------

Description

Batch download of daily gridded DAYMET climate data

Usage

```
download.daymet(years, tile, data.type = "all", download.folder = getwd(),
  http = "http://daymet.ornl.gov/thredds/fileServer/ornl daac/1219/tiles")
```

Arguments

years	Years to download (valid years 1980-2012)
tile	Tile index value (see url for tile index grid in notes section)
data.type	Typ of climate metric: 'all', 'vp', 'tmin', 'tmax', 'swe', 'srad', 'prcp', 'dayl'.
download.folder	local download directory, defaults to current working directory
http	option to change URL

Value

DAYMET netCDF format climate metrics

Note

Available products

vp Water Vapor Pressure Daily average partial pressure of water vapor

tmin Daily minimum (degrees C) 2-meter air temperature

tmax Daily maximum (degrees C) 2-meter air temperature

swe Snow water equivalent (kg/m²). Amount of water contained within snowpack.

srad Incident shortwave radiation flux density (W/m²), taken as average over daylight period of the day.

prcp Daily total precipitation(mm/day), sum of all forms converted to water-equivalent.

dayl Duration of the daylight period for the day (s/day). Calculation is based on the period of the day during which the sun is above a hypothetical flat horizon.

DAYMET main website: <http://daymet.ornl.gov>

Tile index information <http://daymet.ornl.gov/datasupport.html>

Data respository url: <http://daymet.ornl.gov/thredds/fileServer/ornl/daac/1219/tiles>

Path structure: /year/tile_year/file.nc

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Thornton P.E., S.W. Running and M.A. White (1997) Generating surfaces of daily meteorological variables over large regions of complex terrain. *Journal of Hydrology* 190: 214-251.

Thornton, P.E. and S.W. Running (1999) An improved algorithm for estimating incident daily solar radiation from measurements of temperature, humidity, and precipitation. *Agriculture and Forest Meteorology*. 93:211-228.

Thornton, P.E., H. Hasenauer and M.A. White (2000) Simultaneous estimation of daily solar radiation and humidity from observed temperature and precipitation: An application over complex terrain in Austria. *Agricultural and Forest Meteorology* 104:255-271.

Examples

```
## Not run:
# Download 2009-2010 min and max temp for tiles 11737 and 11738
laramie.plains <- c(11737, 11738)
my.years <- c(seq(2009,2010,1))
download.daymet(years=my.years, tile=laramie.plains, data.type=c('tmin','tmax'))

## End(Not run)
```

download.hansen

Download Hansen Forest 2000-2013 Change

Description

Download of Hansen Global Forest Change 2000-2013

Usage

```
download.hansen(tile, data.type = c("loss"), download.folder = getwd())
```

Arguments

tile	Granule index (See project URL for granule grid index)
data.type	Type of data to download options: 'treecover2000', 'loss', 'gain', 'lossyear', 'datamask', 'first', 'last'
download.folder	Destination folder

Value

Downloaded Hansen forest loss tif files

Note

Project website with 10x10 degree granule index: http://earthenginepartners.appspot.com/science-2013-global-forest/download_v1.1.html

Available products: treecover2000, loss, gain, lossyear, datamask, first, or last

'treecover2000' (Tree canopy cover for year 2000) - Tree cover in the year 2000, defined as canopy closure for all vegetation taller than 5m in height. Encoded as a percentage per output grid cell, in the range 0-100.

'loss' (Global forest cover loss 2000-2013) - Forest loss during the period 2000-2013, defined as a stand-replacement disturbance, or a change from a forest to non-forest state. Encoded as either 1 (loss) or 0 (no loss).

'gain' (Global forest cover gain 2000-2012) - Forest gain during the period 2000-2012, defined as the inverse of loss, or a non-forest to forest change entirely within the study period. Encoded as either 1 (gain) or 0 (no gain).

'lossyear' (Year of gross forest cover loss event) - A disaggregation of total forest loss to annual time scales. Encoded as either 0 (no loss) or else a value in the range 1-13, representing loss detected primarily in the year 2001-2013.

'datamask' (Data mask) - Three values representing areas of no data (0), mapped land surface (1), and permanent water bodies (2).

'first' (Circa year 2000 Landsat 7 cloud-free image composite) - Reference multispectral imagery from the first available year, typically 2000. If no cloud-free observations were available for year 2000, imagery was taken from the closest year with cloud-free data, within the range 1999-2012.

'last' (Circa year 2013 Landsat cloud-free image composite) - Reference multispectral imagery from the last available year, typically 2013. If no cloud-free observations were available for year 2013, imagery was taken from the closest year with cloud-free data, within the range 2010-2012.

Author(s)

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References

Hansen, M. C., P. V. Potapov, R. Moore, M. Hancher, S. A. Turubanova, A. Tyukavina, D. Thau, S. V. Stehman, S. J. Goetz, T. R. Loveland, A. Kommareddy, A. Egorov, L. Chini, C. O. Justice, and J. R. G. Townshend. (2013) High-Resolution Global Maps of 21st-Century Forest Cover Change. *Science* 342:850-53.

Examples

```
## Not run:  
# Download single tile  
download.hansen(tile=c('00N', '130E'), data.type=c('loss', 'lossyear'),  
                download.folder=getwd())
```

```
# Batch download of multiple tiles
tiles <- list(c('00N', '140E'), c('00N', '130E'))
for( j in 1:length(tiles)){
  download.hansen(tile=tiles[[j]], data.type=c('loss'))
}

## End(Not run)
```

download.prism

Download PRISM

Description

Batch download of monthly gridded PRISM climate data

Usage

```
download.prism(data.type, date.range, time.step = "monthly",
  download.folder = getwd(), by.year = FALSE, unzip.file = TRUE,
  ftp.site = "ftp://prism.oregonstate.edu")
```

Arguments

data.type	Specify climate metric ('ppt','tmin','tmax','tmean')
date.range	A vector with start and end date in y/m/d format
time.step	Timestep of product ('daily'/'monthly')
download.folder	Local download directory, defaults to current working directory
by.year	Create a directory for each year (TRUE/FALSE)
unzip.file	Unzip file on download (TRUE/FALSE)
ftp.site	PRISM ftp address to use, default: ftp://prism.oregonstate.edu

Value

Compressed or uncompressed PRISM monthly gridded data(bil raster format)

Note

Monthly data 1895-1980 is available in a single zip file on the ftp site

PRISM URL: <http://prism.nacse.org/>

FTP download sites for 400m gridded daily/monthly climate data

<ftp://prism.oregonstate.edu/daily>

<ftp://prism.oregonstate.edu/monthly>

Naming convention: PRISM_<var>_<stability>_<scale&version>_<date>_bil.zip

i.e., 'PRISM_ppt_stable_4kmD1_20100208_bil.zip'

Data description:

http://prism.nacse.org/documents/PRISM_datasets_aug2013.pdf

depends: RCurl

Author(s)

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Examples

```
## Not run:
my.dates <- c('2000/1/1', '2001/12/30')
download.prism('ppt', date.range=my.dates, time.step='monthly', by.year=TRUE)

# Download monthly precipitation data Jan 1st 2000 to Feb 10th 2000 (n=41)
my.dates <- c('2000/1/1', '2000/2/10')
download.prism('ppt', date.range=my.dates, time.step='daily', by.year=TRUE)

## End(Not run)
```

group.pdf

Probability density plot by group

Description

Creates a probability density plot of y for each group of x

Usage

```
group.pdf(x, y, col = NULL, lty = NULL, lwd = NULL, lx = "topleft",
  ly = NULL, ...)
```

Arguments

x	Numeric, character or factorial vector of grouping variable (must be same length as y)
y	Numeric vector (density variable)
col	Optional line colors (see par, col)
lty	Optional line types (see par, lty)
lwd	Optional line widths (see par, lwd)
lx	Position of legend (x coordinate or 'topright', 'topleft', 'bottomright', 'bottom-left')
ly	Position of legend (y coordinate)
...	Additional arguments passed to plot

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Simonoff, J. S. (1996). Smoothing Methods in Statistics. Springer-Verlag, New York.

Examples

```
y=dnorm(runif(100))
x=rep(c(1,2,3), length.out=length(y))
group.pdf(x=as.factor(x), y=y, main='Probability Density of y by group(x)',
ylab='PDF', xlab='Y', lty=c(1,2,3))
```

hexagons

Hexagons

Description

Create hexagon polygons

Usage

```
hexagons(x, res = 100, ...)
```

Arguments

x	sp SpatialDataFrame class object
res	Area of resulting hexagons
...	Additional arguments passed to spsample

Value

SpatialPolygonsDataFrame OBJECT

Note

depends: sp

Examples

```
require(sp)
data(meuse)
coordinates(meuse) <- ~x+y

hex.polys <- hexagons(meuse, res=100)
plot(hex.polys)
plot(meuse,pch=20,add=TRUE)

# Points intersecting hexagons
hex.pts <- na.omit(over(meuse,hex.polys))
(hex.pts <- data.frame(PTID=rownames(hex.pts), hex.pts))
```

idw.smoothing	<i>idw.smoothing</i>
---------------	----------------------

Description

Distance weighted smoothing of a variable in a spatial point object

Usage

```
idw.smoothing(x, y, d, k)
```

Arguments

x	Object of class SpatialPointsDataFrame
y	Numeric data in x@data
d	Distance constraint
k	Maximum number of k-nearest neighbors within d

Value

A vector, same length as nrow(x), of adjusted y values

Note

Smoothing is conducted with a weighted-mean where; weights represent inverse standardized distance lags Distance-based or neighbor-based smoothing can be specified by setting the desired neighbor smoothing method to a specified value then the other parameter to the potential maximum. For example; a constraint distance, including all neighbors within 1000 (d=1000) would require k to equal all of the potential neighbors (n-1 or k=nrow(x)-1).

Depends: sp, RANN

Examples

```

library(sp)
data(meuse)
coordinates(meuse) <- ~x+y

# Calculate distance weighted mean on cadmium variable in meuse data
cadmium.idw <- idw.smoothing(meuse, 'cadmium', k=nrow(meuse), d = 1000)
meuse@data$cadmium.wm <- cadmium.idw
opar <- par
par(mfrow=c(2,1))
plot(density(meuse@data$cadmium), main='Cadmium')
plot(density(meuse@data$cadmium.wm), main='IDW Cadmium')
par <- opar

```

kl.divergence

Kullback-Leibler divergence (relative entropy)

Description

Calculates the Kullback-Leibler divergence (relative entropy) between unweighted theoretical component distributions. Divergence is calculated as: $\int [f(x) (\log f(x) - \log g(x)) dx]$ for distributions with densities $f()$ and $g()$.

Usage

```
kl.divergence(object, eps = 10^-4, overlap = TRUE)
```

Arguments

object	Matrix or dataframe object with ≥ 2 columns
eps	Probabilities below this threshold are replaced by this threshold for numerical stability.
overlap	Logical, do not determine the KL divergence for those pairs where for each point at least one of the densities has a value smaller than eps.

Value

pairwise Kullback-Leibler divergence index (matrix)

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Kullback S., and R. A. Leibler (1951) On information and sufficiency. The Annals of Mathematical Statistics 22(1):79-86

Examples

```
x <- seq(-3, 3, length=200)
y <- cbind(n=dnorm(x), t=dt(x, df=10))
matplot(x, y, type='l')
kl.divergence(y)

# extract value for last column
kl.divergence(y[,1:2])[3:3]
```

land.metrics

*Landscape metrics for points and polygons***Description**

Calculates a variety of landscape metrics, on binary rasters, for polygons or points with a buffer distance

Usage

```
land.metrics(x, y, bkgd = NA, metrics = c(4, 14, 33, 34, 35, 37, 38),
  bw = 1000, latlon = FALSE, Trace = TRUE)
```

Arguments

x	SpatialPointsDataFrame or SpatialPolgonsDataFrame class object
y	raster class object (binary raster)
bkgd	Background value
metrics	Numeric index of desired metrice (see available metrics)
bw	Buffer distance (ignored if x is SpatialPolgonsDataFrame)
latlon	Is raster data in lat-long (TRUE/FALSE)
Trace	Plot raster subsets and echo object ID at each iteration (TRUE FALSE)

Value

data.frame with specified metrics in columns. The data.frame is ordered the same as the input feature class and can be directly joined to the @data slot

Note

[1]class, [2]n.patches, [3]total.area, [4]prop.landscape [5]patch.density, [6]total.edge, [7]edge.density, [8]landscape.shape.index [9]largest.patch.index, [10]mean.patch.area, [11]sd.patch.area, [12]min.patch.area [13]max.patch.area, [14]perimeter.area.frac.dim, [15]mean.perim.area.ratio, [16]sd.perim.area.ratio [17]min.perim.area.ratio, [18]max.perim.area.ratio, [19]mean.shape.index, [20]sd.shape.index [21]min.shape.index, [22]max.shape.index, [23]mean.frac.dim.index, [24]sd.frac.dim.index [25]min.frac.dim.index, [26]max.frac.dim.index, [27]total.core.area, [28]prop.landscape.core [29]mean.patch.core.area, [30]sd.patch.core.area, [31]min.patch.core.area, [32]max.patch.core.area [33]prop.like.adjacencies, [34]aggregation.index, [35]lanscape.division.index, [36]splitting.index [37]effective.mesh.size, [38]patch.cohesion.index

depends: sp, raster, rgeos, SDMTTools

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

Examples

```
require(raster)
require(sp)
r <- raster(ncol=1000, nrow=1000)
r[] <- rpois(ncell(r), lambda=1)
r <- calc(r, fun=function(x) { x[x >= 1] <- 1; return(x) })
xy <- SpatialPointsDataFrame(SpatialPoints(cbind(-50, seq(-80, 80, by=20))),
                             data.frame(ID=seq(1,9,1)))

land.metrics(x=xy, y=r, bw=0.72, bkgd = 0, Trace=FALSE)
```

logistic.regression *Logistic and Auto-logistic regression*

Description

Performs a logistic (binomial) and auto-logistic (spatially lagged binomial) regression

Usage

```
logistic.regression(ldata, y, x, penalty = TRUE, autologistic = FALSE,
                    coords = NULL, bw = NULL, type = "inverse", style = "W",
                    longlat = FALSE, ...)
```

Arguments

ldata	data.frame object containing variables
y	Dependent variable (y) in ldata
x	Independent variable(s) (x) in ldata
penalty	Apply regression penalty (TRUE/FALSE)
autologistic	Add auto-logistic term (TRUE/FALSE)
coords	Geographic coordinates for auto-logistic model
bw	Distance bandwidth to calculate spatial lags (if empty neighbors result, need to increase bandwidth)
type	Neighbor weighting scheme (see autocov_dist)
style	Type of neighbor matrix (W _{ij}), default is mean of neighbors
longlat	Are coordinates (coords) in geographic, lat/long (TRUE/FALSE)
...	Additional arguments passed to lrm

Value

A list class object with the following components:

model lrm model object (rms class)

diagTable data.frame of regression diagnostics

coefTable data.frame of regression coefficients

Residuals data.frame of residuals and standardized residuals

AutoCov If an auto-logistic model, AutoCov represents lagged auto-covariance term

Note

Spatially lagged y defined as:

$$W(y)_{ij} = \frac{\sum_j (W_{ij} y_j)}{\sum_j (W_{ij})}$$

where; $W_{ij} = 1/\text{Euclidian}[i,j]$

depends: rms, spdep

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Le Cessie S, Van Houwelingen JC (1992) Ridge estimators in logistic regression. *Applied Statistics* 41:191-201

Shao J (1993) Linear model selection by cross-validation. *JASA* 88:486-494

Examples

```
require(sp)
require(spdep)
require(rms)
data(meuse)
coordinates(meuse) <- ~x+y
meuse@data <- data.frame(DepVar=rbinom(dim(meuse)[1], 1, 0.5), meuse@data)

#### Logistic model
lmodel <- logistic.regression(meuse@data, y='DepVar', x=c('dist','cadmium','copper'))
lmodel$model
lmodel$diagTable
lmodel$coefTable

### Auto-logistic model using 'autocov_dist' in 'spdep' package
lmodel <- logistic.regression(meuse@data, y='DepVar', x=c('dist','cadmium','copper'),
                             autocov=TRUE, coords=coordinates(meuse), bw=5000)

lmodel$model
lmodel$diagTable
lmodel$coefTable
est <- predict(lmodel$model, type='fitted.ind')
```

```
#### Add residuals, standardized residuals and estimated probabilities
VarNames <- rownames(lmodel$model$var)[-1]
meuse@data$AutoCov <- lmodel$AutoCov
meuse@data <- data.frame(meuse@data, Residual=lmodel$Residuals[,1],
                        StdResid=lmodel$Residuals[,2], Probs=predict(lmodel$model,
                        meuse@data[,VarNames],type='fitted') )

#### Plot fit and probabilities
resid(lmodel$model, "partial", pl="loess")
resid(lmodel$model, "partial", pl=TRUE)           # plot residuals
resid(lmodel$model, "gof")                       # global test of goodness of fit
lp1 <- resid(lmodel$model, "lp1")                # Approx. leave-out linear predictors
-2 * sum(meuse@data$DepVar * lp1 + log(1-plogis(lp1))) # Approx leave-out-1 deviance
spplot(meuse, c('Probs'))                        # plot estimated probs at points
```

moments

moments

Description

Calculate statistical moments of a distribution

Usage

```
moments(x, plot = FALSE)
```

Arguments

x	numeric vector
plot	plot of distribution (TRUE/FALSE)

Value

A vector with the following values

min Minimum

25th 25th percentile

mean Arithmetic mean

gmean Geometric mean

hmean Harmonic mean

median 50th percentile

7th5 75th percentile

max Maximum

stdv Standard deviation

var Variance

cv Coefficient of variation (percent)

mad Median absolute deviation
 skew Skewness
 kurt Kurtosis
 nmodes Number of modes
 mode Mode (dominate)

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

Examples

```
x <- runif(1000,0,100)
  ( d <- moments(x, plot=TRUE) )
  ( mode.x <- moments(x, plot=FALSE)[16] )
```

nni *Average Nearest Neighbor Index (NNI)*

Description

Calculates the NNI as a measure of clustering or dispersal

Usage

```
nni(x, win = "hull")
```

Arguments

x An sp point object
 win Type of window 'hull' or 'extent'

Value

NNI value

Note

The nearest neighbor index is expressed as the ratio of the observed distance divided by the expected distance. The expected distance is the average distance between neighbors in a hypothetical random distribution. If the index is less than 1, the pattern exhibits clustering; if the index is greater than 1, the trend is toward dispersion or competition. The Nearest Neighbor Index is calculated as: Nearest Neighbor Distance (observed) $D(nn) = \sum(\min(D_{ij})/N)$ Mean Random Distance (expected) $D(e) = 0.5 \sqrt{A/N}$ Nearest Neighbor Index $NNI = D(nn)/D(e)$ Where; D=neighbor distance, A=Area
 Depends: sp, spatstat

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Clark, P.J., and F.C. Evans (1954) Distance to nearest neighbor as a measure of spatial relationships in populations. *Ecology* 35:445-453

Cressie, N (1991) *Statistics for spatial data*. Wiley & Sons, New York.

Examples

```
require(sp)
data(meuse)
coordinates(meuse) <- ~x+y
nni(meuse)
```

o.ring

Inhomogeneous O-ring

Description

Calculates the inhomogeneous O-ring point pattern statistic (Wiegand & Maloney 2004)

Usage

```
o.ring(x, ...)
```

Arguments

x spatstat ppp object

... additional arguments passed to pcfinhom

Value

plot of o-ring and data.frame with plot labels and descriptions

Note

The function $K(r)$ is the expected number of points in a circle of radius r centered at an arbitrary point (which is not counted), divided by the intensity I of the pattern. The alternative pair correlation function $g(r)$, which arises if the circles of Ripley's K -function are replaced by rings, gives the expected number of points at distance r from an arbitrary point, divided by the intensity of the pattern. Of special interest is to determine whether a pattern is random, clumped, or regular.

Using rings instead of circles has the advantage that one can isolate specific distance classes, whereas the cumulative K -function confounds effects at larger distances with effects at shorter distances. Note that the K -function and the O-ring statistic respond to slightly different biological questions. The accumulative K -function can detect aggregation or dispersion up to a given distance

r and is therefore appropriate if the process in question (e.g., the negative effect of competition) may work only up to a certain distance, whereas the O-ring statistic can detect aggregation or dispersion at a given distance r . The O-ring statistic has the additional advantage that it is a probability density function (or a conditioned probability spectrum) with the interpretation of a neighborhood density, which is more intuitive than an accumulative measure.

Depends: spatstat

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Wiegand T., and K. A. Moloney (2004) Rings, circles and null-models for point pattern analysis in ecology. *Oikos* 104:209-229

Examples

```
require(spatstat)
data(lansing)
x <- spatstat::unmark(split(lansing)$maple)
o.ring(x)
```

optimal.k

optimalK

Description

Find optimal k of k -Medoid partitions using silhouette widths

Usage

```
optimal.k(x, nk = 10, plot = TRUE, cluster = TRUE, clara = FALSE, ...)
```

Arguments

<code>x</code>	Numeric dataframe, matrix or vector
<code>nk</code>	Number of clusters to test (2:nk)
<code>plot</code>	Plot cluster silhouettes(TRUE/FALSE)
<code>cluster</code>	Create cluster object with optimal k
<code>clara</code>	Use clara model for large data
<code>...</code>	Additional arguments passed to clara

Note

Depends: cluster

Author(s)

Jeffrey S. Evans <jeffrey_evans<at>tnc.org>

References

Theodoridis, S. & K. Koutroumbas(2006) Pattern Recognition 3rd ed.

Examples

```
require(cluster)
x <- rbind(cbind(rnorm(10,0,0.5), rnorm(10,0,0.5)),
          cbind(rnorm(15,5,0.5), rnorm(15,5,0.5)))

clust <- optimal.k(x, 20, plot=TRUE, cluster=TRUE)
plot(silhouette(clust), col = c('red', 'green'))
plot(clust, which.plots=1, main='K-Medoid fit')

# Extract multivariate and univariate mediods (class centers)
clust$medoids
pam(x[,1], 1)$medoids

# join clusters to data
x <- data.frame(x, k=clust$clustering)
```

parea.sample

Percent area sample

Description

Creates a point sample of polygons where n is based on percent area

Usage

```
parea.sample(x, pct = 0.1, join = FALSE, msamp = 1, sf = 4046.86,
            stype = "hexagonal", ...)
```

Arguments

x	sp SpatialPolygonsDataFrame object
pct	Percent of area sampled
join	Join polygon attributed to point sample
msamp	Minimum samples
sf	Scaling factor (default is meters to acres conversion factor)
stype	Sampling type ('random', 'regular', 'nonaligned', 'hexagonal')
...	Additional arguments passed to spsample

Value

A SpatialPointsDataFrame with polygon samples

Note

This function results in an adaptive sample based on the area of each polygon

Depends: sp,

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

Examples

```
require(sp)
sr1=Polygons(list(Polygon(cbind(c(180114, 180553, 181127, 181477, 181294, 181007, 180409,
  180162, 180114), c(332349, 332057, 332342, 333250, 333558, 333676,
  332618, 332413, 332349))))), '1')
sr2=Polygons(list(Polygon(cbind(c(180042, 180545, 180553, 180314, 179955, 179142, 179437,
  179524, 179979, 180042), c(332373, 332026, 331426, 330889, 330683,
  331133, 331623, 332152, 332357, 332373))))), '2')
sr=SpatialPolygons(list(sr1,sr2))
srdf=SpatialPolygonsDataFrame(sr, data.frame(row.names=c('1','2'), PIDS=1:2))

ars <- parea.sample(srdf, pct=0.20, stype='random')
plot(srdf)
plot(ars, pch=20, add=TRUE)
```

point.in.poly

Point and Polygon Intersect

Description

Intersects point and polygon feature classes and adds polygon attributes to points

Usage

```
point.in.poly(pts, polys)
```

Arguments

pts sp SpatialPointsDataFrame or SpatialPoints object
 polys sp SpatialPolygonsDataFrame object

Value

A SpatialPointsDataFrame with intersected polygon attributes

Note

Depends: sp

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

Examples

```
require(sp)
data(meuse)
coordinates(meuse) = ~x+y
sr1=Polygons(list(Polygon(cbind(c(180114, 180553, 181127, 181477, 181294, 181007, 180409,
  180162, 180114), c(332349, 332057, 332342, 333250, 333558, 333676,
  332618, 332413, 332349))))), '1')
sr2=Polygons(list(Polygon(cbind(c(180042, 180545, 180553, 180314, 179955, 179142, 179437,
  179524, 179979, 180042), c(332373, 332026, 331426, 330889, 330683,
  331133, 331623, 332152, 332357, 332373))))), '2')
sr3=Polygons(list(Polygon(cbind(c(179110, 179907, 180433, 180712, 180752, 180329, 179875,
  179668, 179572, 179269, 178879, 178600, 178544, 179046, 179110),
  c(331086, 330620, 330494, 330265, 330075, 330233, 330336, 330004,
  329783, 329665, 329720, 329933, 330478, 331062, 331086))))), '3')
sr4=Polygons(list(Polygon(cbind(c(180304, 180403, 179632, 179420, 180304),
  c(332791, 333204, 333635, 333058, 332791))))), '4')
sr=SpatialPolygons(list(sr1,sr2,sr3,sr4))
srdf=SpatialPolygonsDataFrame(sr, data.frame(row.names=c('1','2','3','4'), PIDS=1:4))

# Intersect points with polygons and add polygon IDS to pts@data.
pts.poly <- point.in.poly(meuse, srdf)
head(pts.poly@data)

# Point counts for each polygon
tapply(pts.poly@data$lead, pts.poly@data$PIDS, FUN=length)
```

pp.subsample

Point process random subsample

Description

Generates random subsample based on density estimate of observations

Usage

```
pp.subsample(x, n, window = "hull", sigma = "Scott", wts = NULL,
  gradient = 1, edge = FALSE)
```

Arguments

x	An sp class SpatialPointsDataFrame or SpatialPoints object
n	Number of random samples to generate
window	Type of window (hull or extent)
sigma	Bandwidth selection method for KDE, default is 'Scott'. Options are 'Scott', 'Stoyan', 'Diggle', 'likelihood', and 'geometry'
wts	Optional vector of weights corresponding to point pattern
gradient	A scaling factor applied to the sigma parameter used to adjust the gradient decent of the density estimate. The default is 1, for no adjustment (downweight < 1 upweight > 1)
edge	Apply Diggle edge correction (TRUE/FALSE)

Value

sp class SpatialPointsDataFrame containing random subsamples

Note

The window type creates a convex hull by default or, optionally, uses the maximum extent (envelope).

Available bandwidth selection methods are: Scott (Scott 1992), Scott's Rule for Bandwidth Selection (1st order) Diggle (Berman & Diggle 1989), Minimise the mean-square error via cross validation (2nd order) likelihood (Loader 1999), Maximum likelihood cross validation (2nd order) geometry, Bandwidth is based on simple window geometry (1st order) Stoyan (Stoyan & Stoyan 1995), Based on pair-correlation function (strong 2nd order)

Note; resulting bandwidth can vary widely by method. the 'diggle' method is intended for selecting bandwidth representing 2nd order spatial variation whereas the 'scott' method will represent 1st order trend. the 'geometry' approach will also represent 1st order trend. for large datasets, caution should be used with the 2nd order 'likelihood' approach, as it is slow and computationally expensive. finally, the 'stoyan' method will produce very strong 2nd order results. '

Depends: sp, spatstat

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Berman, M. and Diggle, P. (1989) Estimating weighted integrals of the second-order intensity of a spatial point process. *Journal of the Royal Statistical Society, series B* 51, 81-92. Berman, M. and Diggle, P. (1989) Estimating weighted integrals of the second-order intensity of a spatial point process. *Journal of the Royal Statistical Society, series B* 51, 81-92.

Fithian, W & T. Hastie (2013) Finite-sample equivalence in statistical models for presence-only data. *Annals of Applied Statistics* 7(4): 1917-1939

Hengl, T., H. Sierdsema, A. Radovic, and A. Dilo (2009) Spatial prediction of species distributions from occurrence-only records: combining point pattern analysis, ENFA and regression-kriging. *Ecological Modelling*, 220(24):3499-3511

Loader, C. (1999) *Local Regression and Likelihood*. Springer, New York.

Scott, D.W. (1992) *Multivariate Density Estimation. Theory, Practice and Visualization*. New York, Wiley.

Stoyan, D. and Stoyan, H. (1995) *Fractals, random shapes and point fields: methods of geometrical statistics*. John Wiley and Sons.

Warton, D.i., and L.C. Shepherd (2010) Poisson Point Process Models Solve the Pseudo-Absence Problem for Presence-only Data in Ecology. *The Annals of Applied Statistics*, 4(3):1383-1402

Examples

```
require(spatstat)
require(sp)
data(bei)
trees <- as(bei, 'SpatialPoints')
n=round(length(trees) * 0.10, digits=0)
trees.wrs <- pp.subsample(trees, n=n, window='hull')
plot(trees, pch=19, col='black')
plot(trees.wrs, pch=19, col='red', add=TRUE)
box()
title('10% subsample')
legend('bottomright', legend=c('Original sample', 'Subsample'),
      col=c('black', 'red'), pch=c(19, 19))
```

pseudo.absence

Pseudo-absence random samples

Description

Generates pseudo-absence samples based on density estimate of known locations

Usage

```
pseudo.absence(x, n, window = "hull", Mask = NULL, s = NULL,
  sigma = "Scott", wts = NULL, KDE = FALSE, gradient = 1, p = NULL,
  edge = FALSE)
```

Arguments

x	An sp class SpatialPointsDataFrame or SpatialPoints object
n	Number of random samples to generate
window	Type of window (hull OR extent), overridden if mask provided
Mask	Optional rasterLayer class mask raster. The resolution of the density estimate will match mask.

s	Optional resolution passed to window argument. Caution should be used due to long processing times associated with high resolution. In contrast, coarse resolution can exclude known points.
sigma	Bandwidth selection method for KDE, default is 'Scott'. Options are 'Scott', 'Stoyan', 'Diggle', 'likelihood', and 'geometry'
wts	Optional vector of weights corresponding to point pattern
KDE	save KDE raster (TRUE/FALSE)
gradient	A scaling factor applied to the sigma parameter used to adjust the gradient decent of the density estimate. The default is 1, for no adjustment (downweight < 1 upweight > 1)
p	Minimum value for probability distribution (must be > 0)
edge	Apply Diggle edge correction (TRUE/FALSE)

Value

A list class object with the following components:

sample SpatialPointsDataFrame containing random samples

kde sp RasterLayer class of KDE estimates (IF KDE = TRUE)

sigma Selected bandwidth of KDE

Note

The window type creates a convex hull by default or, optionally, uses the maximum extent (envelope). if a mask is provided the kde will represent areas defined by the mask. this defines the area that pseudo absence data will be generated.'

Available bandwidth selection methods are: Scott (Scott 1992), Scott's Rule for Bandwidth Selection (1st order) Diggle (Berman & Diggle 1989), Minimise the mean-square error via cross validation (2nd order) likelihood (Loader 1999), Maximum likelihood cross validation (2nd order) geometry, Bandwidth is based on simple window geometry (1st order) Stoyan (Stoyan & Stoyan 1995), Based on pair-correlation function (strong 2nd order)

Note; resulting bandwidth can vary widely by method. the 'diggle' method is intended for selecting bandwidth representing 2nd order spatial variation whereas the 'scott' method will represent 1st order trend. the 'geometry' approach will also represent 1st order trend. for large datasets, caution should be used with the 2nd order 'likelihood' approach, as it is slow and computationally expensive. finally, the 'stoyan' method will produce very strong 2nd order results. '

Depends: sp, spatstat, raster

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

- Berman, M. and Diggle, P. (1989) Estimating weighted integrals of the second-order intensity of a spatial point process. *Journal of the Royal Statistical Society, series B* 51, 81-92.
- Fithian, W & T. Hastie (2013) Finite-sample equivalence in statistical models for presence-only data. *Annals of Applied Statistics* 7(4): 1917-1939
- Hengl, T., H. Sierdsema, A. Radovic, and A. Dilo (2009) Spatial prediction of species distributions from occurrence-only records: combining point pattern analysis, ENFA and regression-kriging. *Ecological Modelling*, 220(24):3499-3511
- Loader, C. (1999) *Local Regression and Likelihood*. Springer, New York.
- Scott, D.W. (1992) *Multivariate Density Estimation. Theory, Practice and Visualization*. New York, Wiley.
- Stoyan, D. and Stoyan, H. (1995) *Fractals, random shapes and point fields: methods of geometrical statistics*. John Wiley and Sons.
- Warton, D.i., and L.C. Shepherd (2010) Poisson Point Process Models Solve the Pseudo-Absence Problem for Presence-only Data in Ecology. *The Annals of Applied Statistics*, 4(3):1383-1402

Examples

```
library(sp)
data(meuse)
coordinates(meuse) = ~x+y

pa <- pseudo.absence(meuse, n=100, window='hull', KDE=TRUE, sigma='Diggle', s=50)
col.br <- colorRampPalette(c('blue','yellow'))
plot(pa$kde, col=col.br(10))
plot(meuse, pch=20, cex=1, add=TRUE)
plot(pa$sample, col='red', pch=20, cex=1, add=TRUE)
legend('top', legend=c('Presence', 'Pseudo-absence'),
      pch=c(20,20),col=c('black','red'))

# With clustered data
library(sp)
library(spatstat)
data(bei)
trees <- as(bei, 'SpatialPoints')
trees <- SpatialPointsDataFrame(coordinates(trees),
                              data.frame(ID=1:length(trees)))
trees.abs <- pseudo.absence(trees, n=100, window='extent', KDE=TRUE)

col.br <- colorRampPalette(c('blue','yellow'))
plot(trees.abs$kde, col=col.br(10))
plot(trees, pch=20, cex=0.50, add=TRUE)
plot(trees.abs$sample, col='red', pch=20, cex=1, add=TRUE)
legend('top', legend=c('Presence', 'Pseudo-absence'),
      pch=c(20,20),col=c('black','red'))
```

raster.entropy	<i>Raster Entropy</i>
----------------	-----------------------

Description

Calculates entropy on integer raster (i.e., 8 bit 0-255)

Usage

```
raster.entropy(x, d = 5, filename = FALSE, ...)
```

Arguments

x	object of class raster (requires integer raster)
d	Size of matrix (window)
filename	Raster file written to disk
...	Optional arguments passed to writeRaster or dataType

Value

raster class object or specified format raster written to disk

Note

Entropy calculated as: $H = -\sum(P_i \cdot \ln(P_i))$ where; P_i , Proportion of one value to total values $P_i = n(p)/m$ and m , Number of unique values Expected range: 0 to $\log(m)$ $H=0$ if window contains the same value in all cells. H increases with the number of different values in the window.

Maximum entropy is reached when all values are different, same as $\log(m)$ `max.ent <- function(x) log(length(unique(x)))`

Depends: raster

References

Fuchs M., Hoffmann R., Schwonke F. (2008) Change Detection with GRASS GIS - Comparison of images taken by different sensor. On line at: http://geoinformatics.fsv.cvut.cz/gwiki/Change_Detection_with_GRASS_GIS_-_Comparison_of_images_taken_by_different_sensors

Examples

```
require(raster)
r <- raster(ncols=100, nrows=100)
r[] <- round(runif(ncell(r), 1,8), digits=0)

rEnt <- raster.entropy(r, d=5)
opar <- par
par(mfcol=c(2,1))
plot(r)
```

```

      plot(rEnt)
par(opar)

```

separability	<i>separability</i>
--------------	---------------------

Description

Calculates variety of univariate or multivariate separability metrics for two class samples

Usage

```

separability(x, y, plot = FALSE, cols = c("red", "blue"),
            clabs = c("Class1", "Class2"), ...)

```

Arguments

x	X vector
y	Y vector
plot	plot separability (TRUE/FALSE)
cols	colors for plot (must be equal to number of classes)
clabs	labels for two classes
...	additional arguments passes to plot

Value

A data.frame with the following separability metrics:

B Bhattacharyya distance statistic

JM Jeffries-Matusita distance statistic

M M-Statistic

D Divergence index

TD Transformed Divergence index

Note

M-Statistic (Kaufman & Remer 1994) - This is a measure of the difference of the distributional peaks. A large M-statistic indicates good separation between the two classes as within-class variance is minimized and between-class variance maximized ($M < 1$ poor, $M > 1$ good).

Bhattacharyya distance (Bhattacharyya 1943; Harold 2003) - Measures the similarity of two discrete or continuous probability distributions.

Jeffries-Matusita distance (Bruzzone et al., 2005; Swain et al., 1971) - The J-M distance is a function of separability that directly relates to the probability of how good a resultant classification will be. The J-M distance is asymptotic to $\sqrt{2}$, where values of $\sqrt{2}$ suggest complete separability

Divergence and transformed Divergence (Du et al., 2004) - Maximum likelihood approach. Transformed divergence gives an exponentially decreasing weight to increasing distances between the classes.

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

- Anderson, M. J., & Clements, A. (2000) Resolving environmental disputes: a statistical method for choosing among competing cluster models. *Ecological Applications* 10(5):1341-1355
- Bhattacharyya, A. (1943) On a measure of divergence between two statistical populations defined by their probability distributions'. *Bulletin of the Calcutta Mathematical Society* 35:99-109
- Bruzzone, L., F. Roli, S.B. Serpico (1995) An extension to multiclass cases of the Jefferys-Matusita distance. *IEEE Transactions on Pattern Analysis and Machine Intelligence* 33:1318-1321
- Du, H., C.I. Chang, H. Ren, F.M. D'Amico, J. O. Jensen, J., (2004) New Hyperspectral Discrimination Measure for Spectral Characterization. *Optical Engineering* 43(8):1777-1786.
- Kailath, T., (1967) The Divergence and Bhattacharyya measures in signal selection. *IEEE Transactions on Communication Theory* 15:52-60
- Kaufman Y., and L. Remer (1994) Detection of forests using mid-IR reflectance: An application for aerosol studies. *IEEE T. Geosci.Remote.* 32(3):672-683.

Examples

```
norm1 <- dnorm(seq(-20,20,length=5000),mean=0,sd=1)
norm2 <- dnorm(seq(-20,20,length=5000),mean=0.2,sd=2)
separability(norm1, norm2)

s1 <- c (1362,1411,1457,1735,1621,1621,1791,1863,1863,1838)
s2 <- c (1362,1411,1457,10030,1621,1621,1791,1863,1863,1838)
separability(s1, s2, plot=TRUE)
```

sp.na.omit

sp.na.omit

Description

Removes row or column NA's in sp object

Usage

```
sp.na.omit(x, margin = 1)
```

Arguments

x Object of class SpatialPointsDataFrame OR SpatialPolygonsDataFrame

margin Margin (1,2) of data.frame 1 for rows or 2 for columns

Note

Depends: sp

Author(s)

Jeffrey S. Evans <jeffrey_evans<at>tnc.org>

Examples

```
require(sp)
data(meuse)
coordinates(meuse) <- ~x+y

# Display rows with NA
meuse@data[!complete.cases(meuse@data),]

# Remove NA's in rows (and associated points)
meuse2 <- sp.na.omit(meuse)
dim(meuse)
dim(meuse2)

# Plot deleted points in red
plot(meuse, col='red', pch=20)
plot(meuse2, col='black', pch=20, add=TRUE)

# Remove columns with NA's
meuse2 <- sp.na.omit(meuse, margin=2)
head(meuse@data)
head(meuse2@data)
```

stratified.random *Stratified random sample*

Description

Creates a stratified random sample of an sp class object

Usage

```
stratified.random(x, strata, n = 10, reps = 1, replace = TRUE)
```

Arguments

x	sp class SpatialDataFrame object (point, polygon, line, pixel)
strata	Column in @data slot with stratification factor
n	Number of random samples
reps	Number of replicates per strata
replace	Sampling with replacement (TRUE FALSE)

Value

sp SpatialDataFrame object (same as input feature) containing random samples

Note

If replace=FALSE features are removed from consideration in subsequent replicates. Conversely, if replace=TRUE, a feature can be selected multiple times across replicates. Not applicable if rep=1.

Depends: sp

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

References

Hudak, A.T., N.L. Crookston, J.S. Evans, M.J. Falkowski, A.M.S. Smith, P. Gessler and P. Morgan. (2006) Regression modeling and mapping of coniferous forest basal area and tree density from discrete-return lidar and multispectral satellite data. Canadian Journal of Remote Sensing 32: 126-138.

Examples

```
require(sp)
data(meuse)
coordinates(meuse) <- ~x+y

# Create stratified variable using quartile breaks
x1 <- cut(meuse@data[, 'cadmium'], summary(meuse@data[, 'cadmium'])[-4], include.lowest=TRUE)
levels(x1) <- seq(1,nlevels(x1),1)
x2 <- cut(meuse@data[, 'lead'], summary(meuse@data[, 'lead'])[-4], include.lowest=TRUE)
levels(x2) <- seq(1,nlevels(x2),1)
meuse@data <- cbind(meuse@data, STRAT=paste(x1, x2, sep='.'))

# 2 replicates and replacement
ssample <- stratified.random(meuse, strata='STRAT', n=2, reps=2)

# 2 replicates and no replacement
ssample.nr <- stratified.random(meuse, strata='STRAT', n=2, reps=2, replace=FALSE)

# n=1 and reps=10 for sequential numbering of samples
ssample.ct <- stratified.random(meuse, strata='STRAT', n=1, reps=10, replace=TRUE)

# Counts for each full strata (note; 2 strata have only 1 observation)
tapply(meuse@data$STRAT, meuse@data$STRAT, length)

# Counts for each sampled strata, with replacement
tapply(ssample@data$STRAT, ssample@data$STRAT, length)

# Counts for each sampled strata, without replacement
tapply(ssample.nr@data$STRAT, ssample.nr@data$STRAT, length)
```

```
# Counts for each sampled strata, without replacement
tapply(ssample.ct@data$STRAT, ssample.ct@data$STRAT, length)

# Plot random samples colored by replacement
ssample@data$REP <- factor(ssample@data$REP)
  spplot(ssample, 'REP', col.regions=c('red','blue'))
```

trend.line

trend.line

Description

Calculated specified trend line of x,y

Usage

```
trend.line(x, y, type = "linear", plot = TRUE, ...)
```

Arguments

x	Vector of x
y	Vector of y
type	Trend line types are: 'linear', 'exponential', 'logarithmic', 'polynomial'
plot	plot results (TRUE/FALSE)
...	Additional arguments passed to plot

Value

A list class object with the following components: for type = 'linear' x is slope and y is intercept for type = 'exponential', 'logarithmic', or 'polynomial' x is original x variable and y is vector of fit regression line

Author(s)

Jeffrey S. Evans <jeffrey_evans@tnc.org>

Examples

```
x <- 1:10
y <- jitter(x^2)
opar <- par
par(mfcol=c(2,2))
  trend.line(x,y,type='linear',plot=TRUE,pch=20,main='Linear')
  trend.line(x,y,type='exponential',plot=TRUE,pch=20,main='Exponential')
  trend.line(x,y,type='logarithmic',plot=TRUE,pch=20,main='Logarithmic')
  trend.line(x,y,type='polynomial',plot=TRUE,pch=20,main='Polynomial')
par <- opar
```

wt.centroid	<i>Weighted centroid</i>
-------------	--------------------------

Description

Creates centroid of [x,y] coordinates based on a weights field

Usage

```
wt.centroid(x, p, sp = TRUE)
```

Arguments

x	sp SpatialPointsDataFrame class object
p	Weights column in x@data slot
sp	Output sp SpatailPoints class object (TRUE FALSE)

Value

A vector or an sp class SpatialPoints object of the weighted coordinate centroid

Note

THE weighted centroid is calculated as: $[Xw]=[X]*[p]$, $[Yw]=[Y]*[p]$, $[sXw]=SUM[Xw]$, $[sYw]=SUM[Yw]$, $[sP]=SUM[p]$ $wX=[sXw]/[sP]$, $wY=[sYw]/[sP]$ where; X=X COORDINATE(S), Y=Y COORDINATE(S), p=WEIGHT

Depends: sp

Examples

```
require(sp)
data(meuse)
coordinates(meuse) = ~x+y
wt.copper <- wt.centroid(meuse, 'copper', sp=TRUE)
wt.zinc <- wt.centroid(meuse, 'zinc', sp=TRUE)
plot(meuse, pch=20, cex=0.75, main='Weighted centroid(s)')
  points(wt.copper, pch=19, col='red', cex=1.5)
  points(wt.zinc, pch=19, col='blue', cex=1.5)
  box()
legend('topleft', legend=c('all', 'copper', 'zinc'),
  pch=c(20,19,19),col=c('black', 'red', 'blue'))
```

`zonal.stats`*zonal.stats*

Description

Polygon zonal statistics of a raster

Usage

```
zonal.stats(x, y, stat, trace = TRUE, plot = TRUE)
```

Arguments

<code>x</code>	Polygon object of class <code>SpatialPolygonsDataFrame</code>
<code>y</code>	Raster object of class <code>raster</code>
<code>stat</code>	Statistic or function
<code>trace</code>	Should progress counter be displayed
<code>plot</code>	Should subset polygons/rasters be plotted (TRUE/FALSE)

Value

Vector, length of `nrow(x)`, of function results

Note

This function iterates through a polygon object, masks the raster to each subset polygon and then coerces the subset raster to a vector object. The resulting vector is then passed to the specified statistic/function. This is much slower than zonal functions available in GIS software but has the notable advantage of being able to accept any custom function, passed to the 'stat' argument, appropriate for a vector object (see example).

Depends: `sp`, `raster`

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Examples

```
# skewness function
skew <- function(x, na.rm=FALSE) {
  if (na.rm)
    x <- x[!is.na(x)]
  sum( (x - mean(x)) ^ 3 ) / ( length(x) * sd(x) ^ 3 )
}

# percent x >= p function
pct <- function(x, p=0.30) {
```

```
if ( length(x[x >= p]) < 1 ) return(0)
  if ( length(x[x >= p]) == length(x) ) return(1)
  else return( length(x[x >= p]) / length(x) )
}

# create some example data
require(raster)
require(sp)
p <- raster(nrow=10, ncol=10)
p[] <- runif(ncell(p)) * 10
p <- rasterToPolygons(p, fun=function(x){x > 9})
r <- raster(nrow=100, ncol=100)
r[] <- runif(ncell(r))
plot(r)
plot(p, add=TRUE, lwd=4)

# run zonal statistics using skew and pct functions
z.skew <- zonal.stats(x=p, y=r, stat=skew, trace=TRUE, plot=TRUE)
z.pct <- zonal.stats(x=p, y=r, stat=pct, trace=TRUE, plot=TRUE)
( z <- data.frame(ID=as.numeric(as.character(row.names(p@data))),
                  SKEW=z.skew, PCT=z.pct) )
```

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