

Package ‘simmer’

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Type Package

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Title Discrete-Event Simulation for R

Description A process-oriented and trajectory-based Discrete-Event Simulation (DES) package for R. Designed to be a generic framework, it leverages the power of 'Rcpp' to boost the performance, turning DES in R feasible. As a noteworthy characteristic, 'simmer' exploits the concept of trajectory: a common path in the simulation model for entities of the same type.

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URL <http://r-simmer.org>

BugReports <https://github.com/r-simmer/simmer/issues>

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add_generator	<i>Add a generator</i>
---------------	------------------------

Description

Define a new generator of arrivals in a simulation environment.

Usage

```
add_generator(env, name_prefix, trajectory, dist, mon = 1, priority = 0,
             preemptible = priority, restart = FALSE)
```

Arguments

env	the simulation environment.
name_prefix	the name prefix of the generated arrivals.
trajectory	the trajectory that the generated arrivals will follow (see create_trajectory).
dist	a function modelling the interarrival times (returning a negative value stops the generator).
mon	whether the simulator must monitor the generated arrivals or not (0 = no monitoring, 1 = simple arrival monitoring, 2 = level 1 + arrival attribute monitoring)
priority	the priority of each arrival (a higher integer equals higher priority; defaults to the minimum priority, which is 0).
preemptible	if a seize occurs in a preemptive resource, this parameter establishes the minimum incoming priority that can preempt these arrivals (an arrival with a priority greater than <code>preemptible</code> gains the resource). In any case, <code>preemptible</code> must be equal or greater than <code>priority</code> , and thus only higher priority arrivals can trigger preemption.
restart	whether the activity must be restarted after being preempted.

Value

Returns the simulation environment.

See Also

Convenience functions: [at](#), [from](#), [to](#), [from_to](#).

`add_resource`*Add a resource*

Description

Define a new resource in a simulation environment.

Usage

```
add_resource(env, name, capacity = 1, queue_size = Inf, mon = TRUE,  
             preemptive = FALSE, preempt_order = c("fifo", "lifo"),  
             queue_size_strict = FALSE)
```

Arguments

<code>env</code>	the simulation environment.
<code>name</code>	the name of the resource.
<code>capacity</code>	the capacity of the server.
<code>queue_size</code>	the size of the queue.
<code>mon</code>	whether the simulator must monitor this resource or not.
<code>preemptive</code>	whether arrivals in the server can be preempted or not based on seize priorities.
<code>preempt_order</code>	if the resource is preemptive and preemption occurs with more than one arrival in the server, this parameter defines which arrival should be preempted first. It must be <code>fifo</code> (First In First Out: older preemptible tasks are preempted first) or <code>lifo</code> (Last In First Out: newer preemptible tasks are preempted first).
<code>queue_size_strict</code>	if the resource is preemptive and preemption occurs, this parameter controls whether the <code>queue_size</code> is a hard limit. By default, preempted arrivals go to a dedicated queue, so that <code>queue_size</code> may be exceeded. If this option is <code>TRUE</code> , preempted arrivals go to the standard queue, and the maximum <code>queue_size</code> is guaranteed (rejection may occur).

Value

Returns the simulation environment.

See Also

Convenience functions: [schedule](#).

at	<i>Arrivals at specific times</i>
----	-----------------------------------

Description

Generator convenience function to generate arrivals at specific times.

Usage

```
at(...)
```

Arguments

... a vector or multiple parameters of times at which to initiate an arrival.

Value

Returns a generator function.

See Also

[add_generator](#).

Examples

```
t0 <- create_trajectory() %>% timeout(0)
env <- simmer(verbose=TRUE) %>%
  add_generator("dummy", t0, at(0, c(1,10,30), 40, 43)) %>%
  run(100)
```

batch	<i>Add a batch/separate activity</i>
-------	--------------------------------------

Description

Collect a number of arrivals before they can continue processing or split a previously established batch.

Usage

```
batch(traj, n, timeout = 0, permanent = FALSE, name = "", rule = NULL)
```

```
separate(traj)
```

Arguments

traj	the trajectory object.
n	batch size, accepts a numeric.
timeout	set an optional timer which triggers batches every timeout time units even if the batch size has not been fulfilled, accepts a numeric (0 = disabled).
permanent	if TRUE, batches cannot be split.
name	optional string. Unnamed batches from different batch activities are independent. However, if you want to feed arrivals from different trajectories into a same batch, you need to specify a common name across all your batch activities.
rule	an optional callable object (a function) which will be applied to every arrival to determine whether it should be included into the batch, thus

Value

The trajectory object.

branch	<i>Add a branch activity</i>
--------	------------------------------

Description

Define a fork with N alternative sub-trajectories.

Usage

```
branch(traj, option, continue, ...)
```

Arguments

traj	the trajectory object.
option	a callable object (a function) which must return an integer between 0 and N. A return value equal to 0 skips the branch and continues to the next activity. A returning value between 1 to N makes the arrival to follow the corresponding sub-trajectory.
continue	a vector of N booleans that indicate whether the arrival must continue to the main trajectory after each sub-trajectory or not.
...	N trajectory objects describing each sub-trajectory.

Value

The trajectory object.

clone	<i>Add a clone/synchronize activity</i>
-------	---

Description

A clone activity replicates an arrival n times (the original one + $n-1$ copies). A synchronize activity removes all but one clone.

Usage

```
clone(traj, n, ...)
```

```
synchronize(traj, wait = TRUE, mon_all = FALSE)
```

Arguments

traj	the trajectory object.
n	number of clones, accepts either a numeric or a callable object (a function) which must return a numeric.
...	optional parallel sub-trajectories. Each clone will follow a different sub-trajectory if available.
wait	if FALSE, all clones but the first to arrive are removed. if TRUE (default), all clones but the last to arrive are removed.
mon_all	if TRUE, get_mon_arrivals will show one line per clone.

Value

The trajectory object.

create_trajectory	<i>Create a trajectory</i>
-------------------	----------------------------

Description

This method initialises a trajectory object, which comprises a chain of activities that can be attached to a generator.

Usage

```
create_trajectory(name = "anonymous", verbose = FALSE)
```

Arguments

name	the name of the trajectory.
verbose	enable showing additional information.

Value

Returns an environment that represents the trajectory.

See Also

Methods for dealing with trajectories: [get_head](#), [get_tail](#), [get_n_activities](#), [join](#), [seize](#), [release](#), [seize_selected](#), [release_selected](#), [select](#), [set_prioritization](#), [set_attribute](#), [timeout](#), [branch](#), [rollback](#), [leave](#), [renege_in](#), [renege_abort](#), [clone](#), [synchronize](#), [batch](#), [separate](#).

Examples

```
t0 <- create_trajectory("my trajectory") %>%
  ## add an intake activity
  seize("nurse", 1) %>%
  timeout(function() rnorm(1, 15)) %>%
  release("nurse", 1) %>%
  ## add a consultation activity
  seize("doctor", 1) %>%
  timeout(function() rnorm(1, 20)) %>%
  release("doctor", 1) %>%
  ## add a planning activity
  seize("administration", 1) %>%
  timeout(function() rnorm(1, 5)) %>%
  release("administration", 1)

t0

t1 <- create_trajectory("trajectory with a branch") %>%
  seize("server", 1) %>%
  # 50-50 chance for each branch
  branch(function() sample(1:2, 1), continue=c(TRUE, FALSE),
    create_trajectory("branch1") %>%
      timeout(function() 1),
    create_trajectory("branch2") %>%
      timeout(function() rexp(1, 3)) %>%
      release("server", 1)
  ) %>%
  # only the first branch continues here
  release("server", 1) %>%
  timeout(function() 2)

t1
```

from

Generate arrivals starting at a specified time

Description

Generator convenience function to generate inter-arrivals with a specified start time.

Usage

```
from(start_time, dist, arrive = TRUE)
```

Arguments

`start_time` the time at which to launch the initial arrival.

`dist` a function modelling the interarrival times.

`arrive` if set to TRUE (default) the first arrival will be generated at `start_time` and will follow `dist` from then on. If set to FALSE, will initiate `dist` at `start_time` (and the first arrival will most likely start at a time later than `start_time`).

Value

Returns a generator function.

See Also

[add_generator](#).

Examples

```
t0 <- create_trajectory() %>% timeout(0)
env <- simmer(verbose=TRUE) %>%
  add_generator("dummy", t0, from(5, function() runif(1, 1, 2))) %>%
  run(10)
```

from_to

Generate arrivals starting and stopping at specified times

Description

Generator convenience function to generate inter-arrivals with specified start and stop times.

Usage

```
from_to(start_time, stop_time, dist, arrive = TRUE)
```

Arguments

`start_time` the time at which to launch the initial arrival.

`stop_time` the time at which to stop the generator.

`dist` a function modelling the interarrival times.

`arrive` if set to TRUE (default) the first arrival will be generated at `start_time` and will follow `dist` from then on. If set to FALSE, will initiate `dist` at `start_time` (and the first arrival will most likely start at a time later than `start_time`).

Value

Returns a generator function.

See Also

[add_generator](#).

Examples

```
t0 <- create_trajectory() %>% timeout(0)
env <- simmer(verbose=TRUE) %>%
  add_generator("dummy", t0, from_to(5, 10, function() runif(1, 1, 2))) %>%
  run(100)
```

get_head

Get the first/last activity

Description

Trajectory getters for obtaining the pointer to its first/last activity.

Usage

```
get_head(traj)
```

```
get_tail(traj)
```

Arguments

traj the trajectory object.

Value

An external pointer to an activity object.

See Also

[get_n_activities](#), [join](#).

get_mon	<i>Get statistics</i>
---------	-----------------------

Description

Simulator getters for obtaining monitored data (if any) about arrivals, attributes and resources.

Usage

```
get_mon_arrivals(envs, per_resource = FALSE, ongoing = FALSE)
```

```
get_mon_attributes(envs)
```

```
get_mon_resources(envs, data = c("counts", "limits"))
```

Arguments

envs	the simulation environment (or a list of environments).
per_resource	if TRUE, statistics will be reported on a per-resource basis.
ongoing	if TRUE, ongoing arrivals will be reported. The columns end_time and finished of these arrivals are reported as NAs.
data	whether to retrieve the "counts", the "limits" or both.

Value

Return a data frame.

get_next_activity	<i>Get the next/prev activity</i>
-------------------	-----------------------------------

Description

It takes an external pointer to an activity and returns the next/prev activity.

Usage

```
get_next_activity(activity)
```

```
get_prev_activity(activity)
```

Arguments

activity	an external pointer to the activity.
----------	--------------------------------------

Value

An external pointer to an activity object.

See Also

[get_head](#), [get_tail](#), [print_activity](#).

<code>get_n_activities</code>	<i>Get the number of activities</i>
-------------------------------	-------------------------------------

Description

Trajectory getter for obtaining the total number of activities defined inside it.

Usage

```
get_n_activities(traj)
```

Arguments

`traj` the trajectory object.

Value

The number of activities in the trajectory.

See Also

[get_head](#), [get_tail](#), [join](#).

<code>get_n_generated</code>	<i>Get the number of arrivals generated</i>
------------------------------	---

Description

Simulator getter for obtaining the number of arrivals generated by a generator by name.

Usage

```
get_n_generated(env, name)
```

Arguments

`env` the simulation environment.
`name` the name of the generator.

Value

Returns a numeric value.

join	<i>Join trajectories</i>
------	--------------------------

Description

Concatenate any number of trajectories in the specified order.

Usage

```
join(...)
```

Arguments

... trajectory objects.

Value

A new trajectory object.

See Also

[get_head](#), [get_tail](#), [get_n_activities](#).

Examples

```
t1 <- create_trajectory() %>% seize("dummy", 1)
t2 <- create_trajectory() %>% timeout(1)
t3 <- create_trajectory() %>% release("dummy", 1)

join(t1, t2, t3)

create_trajectory() %>%
  join(t1) %>%
  timeout(1) %>%
  join(t3)
```

leave	<i>Add a leave activity</i>
-------	-----------------------------

Description

Leave the trajectory with some probability.

Usage

```
leave(traj, prob)
```

Arguments

traj the trajectory object.
prob a probability or a function returning a probability.

Value

The trajectory object.

now *Get current time*

Description

Get the current simulation time.

Usage

now(env)

Arguments

env the simulation environment.

Value

Returns a numeric value.

See Also

[peek](#).

peek *Peek next events*

Description

Look for future events in the event queue and (optionally) obtain info about them.

Usage

peek(env, steps = 1, verbose = FALSE)

Arguments

env	the simulation environment.
steps	number of steps to peek.
verbose	show additional information (i.e., the name of the process) about future events.

Value

Returns numeric values if verbose=F and a data frame otherwise.

See Also

[now](#).

plot_attributes	<i>Plot evolution of attribute data</i>
-----------------	---

Description

Plot the evolution of user-supplied attribute data.

Usage

```
plot_attributes(envs, keys = c())
```

Arguments

envs	a single simmer environment or a list of environments representing several replications.
keys	the keys of attributes you want to plot (if left empty, all attributes are shown).

Value

a ggplot2 object.

See Also

[plot_resource_usage](#), [plot_resource_utilization](#), [plot_evolution_arrival_times](#).

plot_evolution_arrival_times

Plot evolution of arrival times

Description

Plot the evolution of arrival related times (flow, activity and waiting time).

Usage

```
plot_evolution_arrival_times(envs, type = c("activity_time", "waiting_time",
"flow_time"))
```

Arguments

envs	a single simmer environment or a list of environments representing several replications.
type	one of c("activity_time", "waiting_time", "flow_time").

Value

a ggplot2 object.

See Also

[plot_resource_usage](#), [plot_resource_utilization](#), [plot_attributes](#).

plot_resource_usage

Plot usage of a resource over time

Description

Plot the usage of a resource over the simulation time frame.

Usage

```
plot_resource_usage(envs, resource_name, items = c("system", "queue",
"server"), steps = FALSE)
```

Arguments

envs	a single simmer environment or a list of environments representing several replications.
resource_name	the name of the resource (character value).
items	the components of the resource to be plotted.
steps	adds the changes in the resource usage.

Value

a ggplot2 object.

See Also

[plot_resource_utilization](#), [plot_evolution_arrival_times](#), [plot_attributes](#).

`plot_resource_utilization`
Plot utilization of resources

Description

Plot the utilization of specified resources in the simulation.

Usage

```
plot_resource_utilization(envs, resources)
```

Arguments

<code>envs</code>	a single simmer environment or a list of environments representing several replications.
<code>resources</code>	a character vector with at least one resource specified - e.g. "c('res1','res2')".

Value

a ggplot2 object.

See Also

[plot_resource_usage](#), [plot_evolution_arrival_times](#), [plot_attributes](#).

`print_activity` *Print an activity*

Description

It can be used to visualise an activity's internal structure.

Usage

```
print_activity(activity)
```

Arguments

activity an external pointer to the activity.

See Also

[get_head](#), [get_tail](#), [get_next_activity](#), [get_prev_activity](#).

renege_in	<i>Add a renege activity</i>
-----------	------------------------------

Description

Set or unset a timer after which the arrival will abandon.

Usage

```
renege_in(traj, t, out = NULL)
```

```
renege_abort(traj)
```

Arguments

traj the trajectory object.

t timeout to trigger renegeing, accepts either a numeric or a callable object (a function) which must return a numeric.

out optional sub-trajectory in case of renegeing.

Value

The trajectory object.

reset	<i>Reset a simulator</i>
-------	--------------------------

Description

Reset the following components of a simulation environment: time, event queue, resources, generators and statistics.

Usage

```
reset(env)
```

Arguments

env the simulation environment.

Value

Returns the simulation environment.

See Also

[onestep](#), [run](#).

resource	<i>Set/Get a resource's parameters</i>
----------	--

Description

Simulator getters/setters for a resource's server capacity/count and queue size/count.

Usage

```
set_capacity(env, name, value)
get_capacity(env, name)
set_queue_size(env, name, value)
get_queue_size(env, name)
get_server_count(env, name)
get_queue_count(env, name)
```

Arguments

env	the simulation environment.
name	the name of the resource.
value	new value to set.

Value

Return the simulation environment (setters) or a numeric value (getters).

rollback	<i>Add a rollback activity</i>
----------	--------------------------------

Description

Go backwards to a previous point in the trajectory. Useful to implement loops.

Usage

```
rollback(traj, amount, times = 1, check)
```

Arguments

traj	the trajectory object.
amount	the amount of activities (of the same or parent trajectories) to roll back.
times	the number of repetitions until an arrival may continue.
check	a callable object (a function) which must return a boolean. If present, the times parameter is ignored, and the activity uses this function to check whether the rollback must be done or not.

Value

The trajectory object.

run	<i>Run the simulation</i>
-----	---------------------------

Description

Execute steps until the given criterion.

Usage

```
run(env, until = 1000)
```

```
onestep(env)
```

Arguments

env	the simulation environment.
until	stop time.

Value

Returns the simulation environment.

See Also[reset.](#)

schedule	<i>Generate a scheduling object</i>
----------	-------------------------------------

Description

Resource convenience function to generate a scheduling object from a timetable specification.

Usage

```
schedule(timetable, values, period = Inf)
```

Arguments

timetable	absolute points in time in which the desired value changes.
values	one value for each point in time.
period	period of repetition.

Value

Returns a Schedule object.

See Also[add_resource.](#)**Examples**

```
# Schedule 3 units from 8 to 16 h
#           2 units from 16 to 24 h
#           1 units from 24 to 8 h
capacity_schedule <- schedule(c(8, 16, 24), c(3, 2, 1), period=24)

env <- simmer() %>%
  add_resource("dummy", capacity_schedule)
```

 seize

Add a seize/release activity

Description

Activities for seizing/releasing a resource, by name or a previously selected one.

Usage

```
seize(traj, resource, amount = 1, continue = NULL, post.seize = NULL,
      reject = NULL)
```

```
seize_selected(traj, amount = 1, id = 0, continue = NULL,
              post.seize = NULL, reject = NULL)
```

```
release(traj, resource, amount = 1)
```

```
release_selected(traj, amount = 1, id = 0)
```

Arguments

traj	the trajectory object.
resource	the name of the resource.
amount	the amount to seize/release, accepts either a numeric or a callable object (a function) which must return a numeric.
continue	a boolean (if post.seize OR reject is defined) or a pair of booleans (if post.seize AND reject are defined) to indicate whether these subtrajectories should continue to the next activity in the main trajectory.
post.seize	an optional trajectory object which will be followed after a successful seize.
reject	an optional trajectory object which will be followed if the arrival is rejected.
id	selection identifier for nested usage.

Value

The trajectory object.

See Also

[select](#).

select	<i>Select a resource</i>
--------	--------------------------

Description

Resource selector for a subsequent seize/release.

Usage

```
select(traj, resources, policy = c("shortest-queue", "round-robin",
  "first-available", "random"), id = 0)
```

Arguments

traj	the trajectory object.
resources	one or more resource names, or a callable object (a function) which must return a resource name to select.
policy	if resources is a vector of names, this parameter determines the criteria for selecting a resource among the set of policies available; otherwise, it is ignored.
id	selection identifier for nested usage.

Value

The trajectory object.

See Also

[seize_selected](#), [release_selected](#).

set_attribute	<i>Add a set attribute activity</i>
---------------	-------------------------------------

Description

Modify an attribute in the form of a key/value pair.

Usage

```
set_attribute(traj, key, value)
```

Arguments

traj	the trajectory object.
key	the attribute key (coerced to a string).
value	the value to set, accepts either a numeric or a callable object (a function) which must return a numeric.

Value

The trajectory object.

`set_prioritization` *Add a set prioritization activity*

Description

Modify the arrival's prioritization values.

Usage

```
set_prioritization(traj, values)
```

Arguments

<code>traj</code>	the trajectory object.
<code>values</code>	expects either a vector/list or a callable object (a function) returning a vector/list of three values <code>c(priority, preemptible, restart)</code> . A negative value leaves the corresponding parameter unchanged. See add_generator for more information about these parameters.

Value

The trajectory object.

`simmer` *Create a simulator*

Description

This method initialises a simulation environment.

Usage

```
simmer(name = "anonymous", verbose = FALSE)
```

Arguments

<code>name</code>	the name of the simulator.
<code>verbose</code>	enable showing activity information.

Value

Returns a simulation environment.

See Also

Methods for dealing with a simulation environment: [reset](#), [now](#), [peek](#), [onestep](#), [run](#), [add_resource](#), [add_generator](#), [get_mon_arrivals](#), [get_mon_attributes](#), [get_mon_resources](#), [get_n_generated](#), [get_capacity](#), [get_queue_size](#), [set_capacity](#), [set_queue_size](#), [get_server_count](#), [get_queue_count](#).

Examples

```
t0 <- create_trajectory("my trajectory") %>%
  ## add an intake activity
  seize("nurse", 1) %>%
  timeout(function() rnorm(1, 15)) %>%
  release("nurse", 1) %>%
  ## add a consultation activity
  seize("doctor", 1) %>%
  timeout(function() rnorm(1, 20)) %>%
  release("doctor", 1) %>%
  ## add a planning activity
  seize("administration", 1) %>%
  timeout(function() rnorm(1, 5)) %>%
  release("administration", 1)

env <- simmer("SuperDuperSim") %>%
  add_resource("nurse", 1) %>%
  add_resource("doctor", 2) %>%
  add_resource("administration", 1) %>%
  add_generator("patient", t0, function() rnorm(1, 10, 2))

env %>% run(until=80)

plot_resource_usage(env, "doctor")
```

 timeout

Add a timeout activity

Description

Insert delays and execute user-defined tasks.

Usage

```
timeout(traj, task)
```

Arguments

traj the trajectory object.

task the timeout duration supplied by either passing a numeric or a callable object (a function) which must return a numeric (negative values are automatically coerced to positive).

Value

The trajectory object.

to	<i>Generate arrivals stopping at a specified time</i>
----	---

Description

Generator convenience function to generate inter-arrivals with a specified stop time.

Usage

```
to(stop_time, dist)
```

Arguments

stop_time	the time at which to stop the generator.
dist	a function modelling the interarrival times.

Value

Returns a generator function.

See Also

[add_generator](#).

Examples

```
t0 <- create_trajectory() %>% timeout(0)
env <- simmer(verbose=TRUE) %>%
  add_generator("dummy", t0, to(5, function() runif(1, 1, 2))) %>%
  run(10)
```

wrap	<i>Wrap a simulation environment</i>
------	--------------------------------------

Description

This function extracts the monitored data from a simulation environment making it accessible through the same methods. Only useful if you want to parallelize heavy replicas (see the example below), because the C++ simulation backend is destroyed when the threads exit.

Usage

```
wrap(env)
```

Arguments

env the simulation environment.

Value

Returns a simulation wrapper.

See Also

Methods for dealing with a simulation wrapper: [get_mon_arrivals](#), [get_mon_attributes](#), [get_mon_resources](#), [get_n_generated](#), [get_capacity](#), [get_queue_size](#), [get_server_count](#), [get_queue_count](#).

Examples

```
library(parallel)

mm1 <- create_trajectory() %>%
  seize("server", 1) %>%
  timeout(function() rexp(1, 2)) %>%
  release("server", 1)

envs <- mclapply(1:4, function(i) {
  simmer("M/M/1 example") %>%
    add_resource("server", 1) %>%
    add_generator("customer", mm1, function() rexp(1, 1)) %>%
    run(100) %>%
    wrap()
})

plot_resource_usage(envs, "server")
```

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