

Package ‘FLightR’

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Type Package

Title Hidden Markov Model for Solar Geolocation Archival Tags

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Description Estimate positions of animal from data collected by solar geolocation archival tags.

URL <http://github.com/eldarrak/FLightR>

BugReports <http://github.com/eldarrak/FLightR/issues>

Depends R (>= 3.0.2)

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R topics documented:

BAStag2TAGS	2
find.stationary.location	3
find.times.distribution	4
GeoLight2TAGS	5
get.tags.data	6

get_ZI_distances	7
make.calibration	8
make.grid	9
make.prerun.object	10
map.FLightR.ggmap	11
plot_likelihood	13
plot_lon_lat	14
plot_slopes_by_location	15
plot_util_distr	16
run.particle.filter	18
stationary.migration.summary	20
twGeos2TAGS	21

Index 23

BASTag2TAGS	<i>Function to write down twilights annotated in BASTag package data in so-called TAGS format</i>
-------------	---

Description

this function converts combines twilights detected in BASTag with raw data and writes them down in TAGS format that can be easily read by [get.tags.data](#)

Usage

```
BASTag2TAGS(raw, tw1, threshold, filename = NULL)
```

Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
tw1	twilights object from <code>preprocess.light</code> function
threshold	threshold value used for twilight definition in <code>preprocess.light</code>
filename	if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

- datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z
- light light value measured by tag
- twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)
- excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)

- `interp` indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields `excluded` and `interp` may have values of TRUE only for `twilight > 0`.

Value

NULL if `filename` is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

[twGeos2TAGS](#) and [GeoLight2TAGS](#)

find.stationary.location

find unknown calibration location

Description

Functions attempts to find a location where The function attempts to find a location for a time period assuming animal was not moving. Does not work well will shaded data!

Usage

```
find.stationary.location(Proc.data, calibration.start, calibration.stop,
  plot = TRUE, initial.coords = NULL, print.optimization = TRUE,
  reltol = 1e-05)
```

Arguments

<code>Proc.data</code>	processed data object generated by get.tags.data
<code>calibration.start</code>	POSIXct time when stationary period started
<code>calibration.stop</code>	POSIXct time when stationary period ended
<code>plot</code>	plots every iteration
<code>initial.coords</code>	location vector with initial values for location (longitude and latitude). Should be close (+-2000 km from the real location)
<code>print.optimization</code>	do you want every optimization iteration to be printed? If TRUE - Lon, Lat, Calibration mean and Calibration sd are being printed. Optimization tries to minimize the latter.
<code>reltol</code>	tolerance for optimization, see optim for more details

Details

The idea behind the function is that it tries to minimize variance between slopes for the whole period by optimizing location. It can be seen as an extension of Hill-Ekstrom calibration idea.

Author(s)

Eldar Rakhimberdiev

Examples

```
#this example takes about 15 minutes to run
## Not run:
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20")) # end of first calibration period
abline(v=as.POSIXct("2014-05-05")) # start of the second calibration period
Location<-find.stationary.location(Proc.data, '2013-07-20', '2013-08-20', initial.coords=c(10, 50))

## End(Not run)
```

find.times.distribution

extracts times of arrival and departure to/from spatial extent

Description

Idea of this functions is to extract schedules for known location

Usage

```
find.times.distribution(Result, Spatial.Index)
```

Arguments

Result	FLightR result object obtained from run.particle.filter
Spatial.Index	Row numbers for spatial grid (Result\$Spatial\$Grid) to estimate schedules for.

Value

dataframe with columns for 0.025, 0.25, 0.5, 0.75, 0.975 probability of line crossing and rows for every crossing.

Author(s)

Eldar Rakhimberdiev

GeoLight2TAGS	<i>Function to write down twilights annotated in GeoLight package data in so-called TAGS format</i>
---------------	---

Description

this function converts combines twilights detected in BASTag or twGeos with raw data and writes them down in TAGS format that can be easily read by [get.tags.data](#)

Usage

```
GeoLight2TAGS(raw, gl_twl, threshold, filename = NULL)
```

Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
gl_twl	twilights object from GeoLight
threshold	threshold value used for twilight definition in GeoLight
filename	if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

- datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z
- light light value measured by tag
- twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)
- excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)
- interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

Value

NULL if filename is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

[twGeos2TAGS](#) and [BASTag2TAGS](#)

```
get.tags.data      ##@title FLightR ##@import ggplot2 ##@description With a hidden
                    Markov model package estimates postions of animal from data col-
                    lected by solar geolocation archival tags.
```

Description

Reads the data frame with detected twilight events into the FLightR

Usage

```
get.tags.data(filename = NULL, start.date = NULL, end.date = NULL,
  log.light.borders = "auto", log.irrad.borders = "auto",
  saves = c("auto", "max", "mean"), measurement.period = NULL,
  impute.on.boundaries = FALSE)
```

Arguments

filename	the name of the file which the data are to be read from. File is supposed to be comma separated file of TAGS format. If it does not contain an absolute path, the file name is relative to the current working directory, <code>getwd()</code> . Tilde-expansion is performed where supported. This can be a compressed file (see file). Alternatively, file can be a readable text-mode connection (which will be opened for reading if necessary, and if so closed (and hence destroyed) at the end of the function call). File can also be a complete URL. For the supported URL schemes, see help for url .
start.date	date of beginning of relevant data collection in POSIXct format.
end.date	date of end of relevant data collection in POSIXct format.
log.light.borders	Numeric vector with length of 2 for minimum and maximum <code>log(light)</code> levels to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.
log.irrad.borders	Numeric vector with length of 2 for minimum and maximum <code>log(irradiance)</code> values to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.
saves	character values informing FLightR if min or max values were used by logger.
measurement.period	Value in seconds defining how often tag was measuring light levels. If NULL value will be taken from known values for detected tag type.
impute.on.boundaries	logical, if FLightR should approximate values at boundaries. Set it to TRUE only if you have vary few active points at each twilight, e.g if tag was saving every 10 minutes or so.

Details

The returned object has many parts, the important are: (1) the recorded light data, (2) the detected twilight events, (3) light level data at the moment of each determined sunrise and sunset and around them (24 fixes before and 24 after), and (4) technical parameters of the tag, i. e. its type, saving and measuring period (the periodicity, in seconds, at which a tag measures and saves data).

Value

list, which is to be further processed with the FlightR.

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
```

get_ZI_distances	<i>Estimate distances moved between twilights</i>
------------------	---

Description

This function estimate distances with all zeros from stationary periods. This means many of the resulting movements will have 0 as the distance

Usage

```
get_ZI_distances(Result)
```

Arguments

Result An object created by [run.particle.filter](#).

Value

a data frame containing median and quartiles for the distances and also departure and arrival time

Author(s)

Eldar Rakhimberdiev

make.calibration	<i>Creates a calibration object, further used for calculation of coordinates in the <code>run.particle.filter</code>.</i>
------------------	---

Description

Function estimates all necessary parameters from the calibration data logged in a known location or locations.

Usage

```
make.calibration(Proc.data, Calibration.periods, model.ageing = FALSE,
  plot.each = FALSE, plot.final = FALSE, likelihood.correction = "auto",
  suggest.irrad.borders = FALSE)
```

Arguments

Proc.data	processed data object generated by get.tags.data
Calibration.periods	a data frame containing start and end dates of all the calibration periods (POSIXct) and geographic coordinates of the corresponding calibration locations.
model.ageing	if set to TRUE, accounts for the tag ageing (with opacification of its transparent shell of a light sensor), resulting into decreasing sensitivity of the device. This option is useful only if there were several calibration periods or if calibration period was very long (~ longer than a month).
plot.each	Do you want every twilight to be plotted while processing
plot.final	Do you want final calibration graph to be plotted. On the graph you can see all the observed versus expected light levels. All slopes should be similar.
likelihood.correction	will estimate correction of likelihood for the current calibration paramters. Highly recommended not to be change from 'auto'. In this case FLightR will switch it to FALSE in case tage saved dat on 10 minutes or longre period
suggest.irrad.borders	experimental parameter! If set to TRUE faunction will try to find the best velues for the log.irrad.borders

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-08-20', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=NA,
```



```

    calibration.stop=as.POSIXct("2013-08-20"),
    lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default 'auto' for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

```

make.grid	<i>makes spatial grid</i>
-----------	---------------------------

Description

This function makes a rectangular grid with use defined boudnaries and probabilities of being stationary.

Usage

```

make.grid(left = -180, bottom = -90, right = 180, top = 90,
  distance.from.land.allowed.to.use = c(-Inf, Inf),
  distance.from.land.allowed.to.stay = c(-Inf, Inf), plot = TRUE,
  return.distances = FALSE, probability.of.staying = 0.5)

```

Arguments

left	- left boundary in degrees (-180 <= left <= 180)
bottom	- lower boundary in degrees (-90 <= bottom <= 90)
right	- right boundary in degrees (-180 <= right <= 180)
top	- top boundary in degrees (-90 <= right <= 90)
distance.from.land.allowed.to.use	- define how far from the shoreland animal could occur. Unit - km, egative values are for inland and positive for offshore directions. Inf stays for infinity
distance.from.land.allowed.to.stay	- define how far from the shoreland animal could stay stationary between twilights. Unit - km, egative values are for inland and positive for offshore directions. Inf stays for infinity
plot	show a plot of final grid.
return.distances	- return distances to the shoreline
probability.of.staying	- assigned probability value for grid cells that do not satisfy distance.from.water.allowed.to.stay

Value

dataframe with coordinates(lon and lat) and probability.of.staying

Author(s)

Eldar Rakhimberdiev

Examples

```
Grid<-make.grid(left=-14, bottom=30, right=13, top=57,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
```

make.prerun.object *combines data, calibration and sets up priors*

Description

This function is one step before [run.particle.filter](#). It combines data, calibration, spatial extent and movement priors and estimates spatial likelihoods that used later in the particle filter.

Usage

```
make.prerun.object(Proc.data, Grid, start, end = start, Calibration,
  threads = -1, Decision = 0.1, Direction = 0, Kappa = 0,
  M.mean = 300, M.sd = 500, likelihood.correction = TRUE)
```

Arguments

Proc.data	Processed dat aobject created by get.tags.data .
Grid	Spatial grid created by make.grid .
start	release location (lat, lon).
end	end of the track location. Will use start by default. Use NA in case of unknown end point.
Calibration	Calibration object created by make.calibration .
threads	number of parallel threads to use. default is -1, which means FLightR will use all available threads except 1. Value 1 will force sequential evaluation
Decision	prior for migration probability values from 0 to 1 are allowed
Direction	Direction prior for direction of migration (in degrees) with 0 pointing to the North
Kappa	concentration parameter for vonMises distribution, 0 means uniform or even distribution. Will set some prior for direction for all the track, so is not recommended to be changed
M.mean	Prior for mean distance travelled between consecutive twilights, km

M.sd Prior for sd of distance travelled between consecutive twilights, the higher the value is the wider is the the distribution

likelihood.correction Should likelihood correction estimated during `make.calibration` run be used?

Value

Object to be uses in the `run.particle.filter`

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=NA,
  calibration.stop=as.POSIXct("2013-08-20"),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=2)
```

map.FLightR.ggmap *plots result over map*

Description

plots track over map with probability cloud. Can plot only part of the track if dates are specified

Usage

```
map.FLightR.ggmap(Result, dates = NULL, plot.cloud = TRUE,
  map.options = NULL, plot.options = NULL, save.options = NULL,
  zoom = "auto", return.ggobj = FALSE, seasonal.colors = TRUE,
  seasonal.donut.location = "topleft", seasonal.donut.proportion = 0.5,
  save = TRUE)
```

Arguments

Result	FLightR result object obtained from run.particle.filter
dates	either NULL if all twilights should be included or data.frame with first column - start of the period and second end of the period. Each line represents a new period
plot.cloud	Should probability cloud be plotted? If TRUE cloud is estimated by stat_density2d
map.options	options passed to get_map , note that zoom option is defined separately
plot.options	plotting options. Not defined yet!
save.options	ptions passed to ggsave . Filename should be defined here.
zoom	Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downloading different size maps and checking whether all the points fit the map.
return.ggobj	Should ggobj be returned for subsequent checks and/or replotting
seasonal.colors	if true points of the track will have seasonal colors
seasonal.donut.location	if NULL - no color wheel placed, otherwise select one of 'bottomleft', 'bottom-right', 'topleft'
seasonal.donut.proportion	how much of X axis should color wheel occupy. return either NULL or ggplot2 class object
save	should function save results with ggsave ?

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=as.POSIXct(c(NA, "2014-05-05")),
  calibration.stop=as.POSIXct(c("2013-08-20", NA)),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
```

```
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
  nParticles=1e3, known.last=TRUE,
  precision.sd=25, check.outliers=FALSE)

map.FlightR.ggmap(Result, seasonal.donut.location=NULL, zoom=6, save=FALSE)
# for this short track without variance seasonal donut does not work,
# but for normal track it will.
```

plot_likelihood *plot likelihood surface over map*

Description

plots specific likelihood surface over map

Usage

```
plot_likelihood(object, date = NULL, twilight.index = NULL)
```

Arguments

object either output from `make.prerun.object` or `run.particle.filter`

date either NULL or a date (possibly with time) closest to the twilight you want to be plotted

twilight.index number of likelihood surface to be plotted

Details

function plots likelihoods before particle filter run, so these are pure results of calibrations without any movement model

Author(s)

Eldar Rakhimberdiev

Examples

```

File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=as.POSIXct(c(NA, "2014-05-05")),
  calibration.stop=as.POSIXct(c("2013-08-20", NA)),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=2)
plot_likelihood(all.in, twilight.index=10)

```

plot_lon_lat

plots result by longitude and latitude

Description

This function plots result by latitude and longitude in either vertical or horizontal layout

Usage

```
plot_lon_lat(Result, scheme = c("vertical", "horizontal"))
```

Arguments

Result	FLightR result object obtained from run.particle.filter
scheme	either 'vertical' or 'horizontal' layouts return NULL

Author(s)

Eldar Rakhimberdiev

Examples

```

File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=as.POSIXct(c(NA, "2014-05-05")),
  calibration.stop=as.POSIXct(c("2013-08-20", NA)),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
  nParticles=1e3, known.last=TRUE,
  precision.sd=25, check.outliers=FALSE)

plot_lon_lat(Result)

```

```
plot_slopes_by_location
```

plots log of observed vesus expected slope by time for a known location

Description

The function calculates and plots calibration slopes for sunsets and sunrises for every day of the tracking period, based on the assumption that the tag remained in the same (calibration) location all the time.

Usage

```
plot_slopes_by_location(Proc.data, location, log.light.borders = "auto",
  log.irrad.borders = "auto")
```

Arguments

Proc.data	processed data object generated by get.tags.data
location	vector with langitude and latitude of calibration location (degrees).

log.light.borders

Numeric vector with length of 2 for minimum and maximum log(light) levels to use. Default value 'auto', will take these values from the Proc.data object.

log.irrad.borders

Numeric vector with length of 2 for minimum and maximum log(irradiance) values to use. Default value 'auto', will take these values from the Proc.data object.

Details

The plot of calibration slopes is used for finding start and end dates of a calibration period (the time period, during which the tag remained in the calibration location with coordinates (x,y)). During the calibration period, the calibration slopes vary little both, between the twilight events (sunrises and sunsets) and in time. When the tag changes location, the slopes for sunrises and sunsets start to deviate. There may potentially be several calibration periods for the same location (if the bird returned to the same location several times). The boundaries (start and end dates) of each of these periods are captured visually. If there were more than one calibration location, the procedure is repeated, once for each location. All the obtained calibration periods can be entered in a data frame 'Calibration.periods', for further analysis. Each line of the data frame contains start and end dates (if applicable) of the calibration period and geographic coordinates of the location.

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20")) # end of first calibration period
abline(v=as.POSIXct("2014-05-05")) # start of the second calibration period
```

plot_util_distr	<i>plots resulting track over map with uncertainty shown by spave utilization distribution</i>
-----------------	--

Description

May be use not only for the whole track but for a set of specific dates, e.g. to show spatial uncertainty during migration

Usage

```
plot_util_distr(Result, dates = NULL, map.options = NULL,
  percentiles = c(0.4, 0.6, 0.8), zoom = "auto",
  geom_polygon.options = NULL, save.options = NULL, color.palette = NULL,
  use.palette = TRUE, background = NULL, plot = TRUE, save = TRUE,
  add.scale.bar = FALSE, scalebar.options = NULL)
```


Arguments

Result	FLightR result object obtained from run.particle.filter
dates	Use NULL if all twilights will be used for plotting, one integer if specific twilight should be plotted (line number in Result\$Results\$Quantiles). Use data.frame with first column - start of the period and second - end of the period and each line represents a new period to plot specific periods, e.g. wintering or migration.
map.options	options passed to get_map , note that zoom option is defined separately
percentiles	Probability breaks for utilisation distribution
zoom	Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downloading different size maps and checking whether all the points fit the map.
geom_polygon.options	passed to geom_polygon
save.options	ptions passed to ggsave . Filename should be defined here.
color.palette	colors for probability contours. Either NULL or colorRampPalette object
use.palette	should the same colors be used for polygon boundaries as for polygon filling?
background	if provided will be used as a background. Must be created by <code>link[ggmap]{get_map}</code>
plot	should function produce a plot?
save	should function save results with ggsave ?
add.scale.bar	will add scalebar with the scalebar
scalebar.options	options passed to scalebar

Value

list with two parts	
res_buffers	spatial buffers for defined probability values
p	ggplot object

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=as.POSIXct(c(NA, "2014-05-05")),
  calibration.stop=as.POSIXct(c("2013-08-20", NA)),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))

# NB Below likelihood.correction is set to FALSE for fast run!
```

```
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=1)
# here we will run only 1e4 particles for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
  nParticles=1e3, known.last=TRUE,
  precision.sd=25, check.outliers=FALSE)

plot_util_distr(Result, zoom=6, save=FALSE)
```

`run.particle.filter` *Run Particle Filter*

Description

Main function of FLIGHTR, it takes fully prepared object created by [make.prerun.object](#) and produces a result object that can be used for plotting etc.

Usage

```
run.particle.filter(all.out, cpus = NULL, threads = -1,
  nParticles = 1e+06, known.last = TRUE, precision.sd = 25,
  behav.mask.low.value = 0, k = NA, plot = TRUE, cluster.type = "PSOCK",
  a = 45, b = 1500, L = 90, adaptive.resampling = 0.99,
  check.outliers = FALSE, sink2file = FALSE, add.jitter = FALSE)
```

Arguments

<code>all.out</code>	An object created by make.prerun.object .
<code>cpus</code>	another way to specify threads
<code>threads</code>	An amount of threads to use while running in parallel. default is -1. if value 1 submitted package will run sequentially
<code>nParticles</code>	total amount of particles to be used with the run. 10 000 (1e4) is recommended for the preliminary run and 1 000 000 (1e6) for the final
<code>known.last</code>	Set to FALSE if your bird was not at a known place during last twilight in the data
<code>precision.sd</code>	if <code>known.last</code> then what is the precision of this information. Will be used to resample particles proportionally to their distance from the known last point with probability $P = \text{dnorm}(0, \text{precision.sd})$

behav.mask.low.value	Probability value that will be used instead of 0 in the behavioural mask. If set to 1 behavioural mask will not be active anymore
k	Kappa parameter from vonMises distribution. Default is NA, otherwise will generate particles in a direction of a previous transitions with kappa = k
plot	Should function plot preliminary map in the end of the run?
cluster.type	see help to package parallel for details
a	minimum distance that is used in the movement model - left boundary for truncated normal distribtuon of ditances moved between twilights. Default is 45 for as default grid has a minimum dittance of 50 km.
b	Maximum distance allowed to fly between two consecutive twilights
L	how many consecutive particles to resample
adaptive.resampling	Above what level of ESS resampling should be skipped
check.outliers	switches ON the online outlier routine
sink2file	will write run details in a file instead of showing on the screen
add.jitter	will add spatial jitter inside a grid cell for the median estiamtes

Value

FLightR object, containing output and extracted results. It is a list with the following elements

Indices	List with prior information and indices
Spatial	Spatial data - Grid, Mask, spatial likelihood
Calibration	all calibration parameters
Data	original data
Results	The main results object. Main components of it are Quantiles dataframe containing results on locations. Each line corresponds to a twilight Movement.results dataframe containing all the movement results, Note - time at line n means time of the end of transition between n and n-1 outliers id of twilights excluded by online outlier detection tool LL -Log likelihood Points.rle run length encoding object with posterior distribution for every twilight. Note that numbers of points correspond to line numbers in \$Spatial\$Grid Transitions.rle run length encoding object with all the transitions

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=NA,
  calibration.stop=as.POSIXct("2013-08-20"),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
  nParticles=1e3, known.last=TRUE,
  precision.sd=25, check.outliers=FALSE)
```

stationary.migration.summary

find potential stationary periods and estimates their location and movement schedule

Description

This function will find any sites where birds stayed longer than `min.stay`. Potential movement is detected by the minimum probability of movement `prob.cutoff`.

Usage

```
stationary.migration.summary(Result, prob.cutoff = 0.1, min.stay = 3)
```

Arguments

Result	FLightR result object obtained from run.particle.filter
prob.cutoff	Minimum probability that defines movement
min.stay	Minimum duration of stationary period (in twilights)

Value

list with stationary and movement statistics

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(
  calibration.start=as.POSIXct(c(NA, "2014-05-05")),
  calibration.stop=as.POSIXct(c("2013-08-20", NA)),
  lon=5.43, lat=52.93)
#use c() also for the geographic coordinates, if you have more than one calibration location
# (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))

# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)

Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))

all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
  Calibration=Calibration, threads=1)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
  nParticles=1e3, known.last=TRUE,
  precision.sd=25, check.outliers=FALSE)

Summary<-stationary.migration.summary(Result, prob.cutoff=1)
# Use lower cut offs for real runs!
```

twGeos2TAGS

Function to write down twilights annotated in twGeos package data in so-called TAGS format

Description

this function converts combines twilights detected in twGeos with raw data and writes them down in TAGS format that can be easily read by [get.tags.data](#)

Usage

```
twGeos2TAGS(raw, twl, threshold, filename = NULL)
```

Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
twl	twilights object from preprocess.light function
threshold	threshold value used for twilight definition in preprocess.light
filename	if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

- datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z
- light light value measured by tag
- twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)
- excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)
- interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

Value

NULL if filename is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

[BAStag2TAGS](#) and [GeoLight2TAGS](#)

Index

BAStag2TAGS, [2](#), [5](#), [22](#)

colorRampPalette, [17](#)

file, [6](#)

find.stationary.location, [3](#)

find.times.distribution, [4](#)

GeoLight2TAGS, [3](#), [5](#), [22](#)

geom_polygon, [17](#)

get.tags.data, [2](#), [3](#), [5](#), [6](#), [8](#), [10](#), [15](#), [21](#)

get_map, [12](#), [17](#)

get_ZI_distances, [7](#)

ggplot, [17](#)

ggsave, [12](#), [17](#)

make.calibration, [8](#), [10](#), [11](#)

make.grid, [9](#), [10](#)

make.prerun.object, [10](#), [13](#), [18](#)

map.FLightR.ggmap, [11](#)

optim, [3](#)

plot_likelihood, [13](#)

plot_lon_lat, [14](#)

plot_slopes_by_location, [15](#)

plot_util_distr, [16](#)

POSIXct, [6](#)

run.particle.filter, [4](#), [7](#), [8](#), [10–14](#), [17](#), [18](#),
[20](#)

scalebar, [17](#)

stat_density2d, [12](#)

stationary.migration.summary, [20](#)

twGeos2TAGS, [3](#), [5](#), [21](#)

url, [6](#)