

# Package ‘dsm’

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**License** GPL (>= 2)

**Title** Density Surface Modelling of Distance Sampling Data

**LazyLoad** yes

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Sharon Hedley.

**Description** Density surface modelling of line transect data. A Generalized Additive Model-based approach is used to calculate spatially-explicit estimates of animal abundance from distance sampling (also presence/absence and strip transect) data. Several utility functions are provided for model checking, plotting and variance estimation.

**Version** 2.2.15

**URL** <http://github.com/DistanceDevelopment/dsm>

**BugReports** <https://github.com/DistanceDevelopment/dsm/issues>

**Depends** R (>= 3.0), mgcv (>= 1.7), mrds (>= 2.1.16), numDeriv

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 dsm-package

*Density surface modelling*


---

## Description

dsm implements spatial models for distance sampling data.

## Details

Further information on distance sampling methods and example code is available at <http://distancesampling.org/R/>.

For help with distance sampling and this package, there is a Google Group <https://groups.google.com/forum/#!forum/distance-sampling>.

A example analysis is available at <http://distancesampling.org/R/vignettes/mexico-analysis.html>.

---

block.info.per.su      *Find the block information*

---

### Description

Takes the transect data and works out how many blocks of a given size (in segment terms) fit into each.

### Usage

```
block.info.per.su(block.size, data, name.su)
```

### Arguments

block.size	number of segments per block
data	data used to build the model
name.su	names of the sampling units (ie. transects)

### Value

a data.frame with the following columns

name	the sample unit name (e.g. transect label)
num.seg	number of segments in that transect
num.block	number of blocks available
start.block	block # for first block
end.block	block # for last block
num.req	number of blocks needed for the unit

---

check.cols      *Check column names exist*

---

### Description

Internal function to check that supplied 'data.frames' have the correct columns and checks that sample labels are all unique.

### Usage

```
check.cols(ddf.obj, segment.data, observation.data, strip.width, segment.area)
```

**Arguments**

ddf.obj	a ddf object from ‘mrds’
segment.data	segment data as defined in <a href="#">dsm</a>
observation.data	observation data as defined in <a href="#">dsm</a>
strip.width	strip width if strip transects are being used
segment.area	area of segments

**Value**

nothing, but throws an error if something went wrong

**Author(s)**

David Lawrence Miller

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dsm	<i>Fit a density surface model to segment-specific estimates of abundance or density.</i>
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**Description**

Fits a density surface model (DSM) to detection adjusted counts from a spatially-referenced distance sampling analysis. [dsm](#) takes observations of animals, allocates them to segments of line (or strip transects) and optionally adjusts the counts based on detectability using a supplied detection function model. A generalized additive model, generalized mixed model or generalized linear model is then used to model these adjusted counts based on a formula involving environmental covariates.

**Usage**

```
dsm(formula, ddf.obj, segment.data, observation.data, engine = "gam",
    convert.units = 1, family = quasipoisson(link = "log"), group = FALSE,
    gamma = 1.4, control = list(keepData = TRUE), availability = 1,
    strip.width = NULL, segment.area = NULL, weights = NULL,
    transect = "line", method = "REML", ...)
```

**Arguments**

formula	formula for the surface. This should be a valid <a href="#">glm/gam/gamm</a> formula. See "Details", below, for how to define the response.
ddf.obj	result from call to <a href="#">ddf</a> or <a href="#">ds</a> . If ddf.obj is NULL then strip transects are assumed.
segment.data	segment data, see <a href="#">dsm-data</a> .
observation.data	observation data, see <a href="#">dsm-data</a> .

engine	which fitting engine should be used for the DSM ( <a href="#">glm/gam/gamm/bam</a> ).
convert.units	conversion factor to multiply the area of the segments by. See 'Units' below.
family	response distribution (popular choices include <a href="#">quasipoisson</a> , <a href="#">Tweedie/tw</a> and <a href="#">negbin/nb</a> ). Defaults to <a href="#">quasipoisson</a> .
group	if TRUE the abundance of groups will be calculated rather than the abundance of individuals. Setting this option to TRUE is equivalent to setting the size of each group to be 1.
gamma	parameter to <code>gam()</code> set to a value of 1.4 (from advice in Wood (2006)) such that the <code>gam()</code> is inclined to not 'overfit' when GCV is used to select the smoothing parameter (ignored for REML, see <code>link{gam}</code> for further details).
control	the usual control argument for a <code>gam</code> ; <code>keepData</code> must be TRUE for variance estimation to work (though this option cannot be set for GLMs or GAMMs).
availability	an availability bias used to scale the counts/estimated counts by. If we have N animals in a segment, then <code>N/availability</code> will be entered into the model. Uncertainty in the availability is not handled at present.
strip.width	if <code>ddf.obj</code> , above, is NULL, then this is where the strip width is specified (i.e. for a strip transect survey). This is sometimes (and more correctly) referred to as the half-width, i.e. right truncation minus left truncation.
segment.area	if 'NULL' (default) segment areas will be calculated by multiplying the 'Effort' column in 'segment.data' by the (right minus left) truncation distance for the 'ddf.obj' or by 'strip.width'. Alternatively a vector of segment areas can be provided (which must be the same length as the number of rows in 'segment.data') or a character string giving the name of a column in 'segment.data' which contains the areas. If <code>segment.area</code> is specified it takes precedent.
weights	weights for each observation used in model fitting. The default, <code>weights=NULL</code> , weights each observation by its area (see Details). Setting a scalar value (e.g. <code>weights=1</code> ) all observations are equally weighted.
transect	type of transect ("line", the default or "point"). This is overridden by the detection function <code>transect</code> type, this is usually only necessary when no detection function is specified.
method	The smoothing parameter estimation method. Default is "REML", using Restricted Maximum Likelihood. See <a href="#">gam</a> for other options. Ignored for <code>engine="glm"</code> .
...	anything else to be passed straight to <a href="#">glm/gam/gamm/bam</a> .

## Details

The response (LHS of 'formula') can be one of the following:

<code>n, count, N</code>	count in each segment
<code>Nhat, abundance.est</code>	estimated abundance per segment, estimation is via a Horvitz-Thompson estimator. This should be used for point transects.
<code>presence</code>	interpret the data as presence/absence (remember to change the family argument to <code>binomial</code> ).
<code>D, density, Dhat, density.est</code>	density per segment

The offset used in the model is dependent on the response:

count	area of segment multiplied by average probability of detection in the segment
estimated count	area of the segment
presence	zero
density	zero

In the latter two cases (density and presence estimation) observations can be weighted by segment areas via the `weights=` argument. By default (`weights=NULL`), when density or presence are estimated the weights are set to the segment areas (using `segment.area` or by calculating  $2 \times (\text{strip width}) \times \text{Effort}$ ) Alternatively `weights=1` will set the weights to all be equal. A third alternative is to pass in a vector of length equal to the number of segments, containing appropriate weights.

### Value

a `glm/gam/gamm` object, with an additional element, `ddf` which holds the detection function object.

### Units

It is often the case that distances are collected in metres and segment lengths are recorded in kilometres. `dsm` allows you to provide a conversion factor (`convert.units`) to multiply the areas by. For example: if distances are in metres and segment lengths are in kilometres setting `convert.units=1000` will lead to the analysis being in metres. Setting `convert.units=1/1000` will lead to the analysis being in kilometres. The conversion factor will be applied to ‘`segment.area`’ if that is specified.

### Large models

For large models, `engine="bam"` with `method="fREML"` may be useful. Models specified for `bam` should be as `gam`. READ `bam` before using this option; this option is considered EXPERIMENTAL at the moment. In particular note that the default basis choice (thin plate regression splines) will be slow and that in general fitting is less stable than when using `gam`. For negative binomial response, `theta` must be specified when using `bam`.

### Author(s)

David L. Miller

### References

- Hedley, S. and S. T. Buckland. 2004. Spatial models for line transect sampling. *JABES* 9:181-199.
- Miller, D. L., Burt, M. L., Rexstad, E. A., Thomas, L. (2013), Spatial models for distance sampling data: recent developments and future directions. *Methods in Ecology and Evolution*, 4: 1001-1010. doi: 10.1111/2041-210X.12105 (Open Access, available at <http://onlinelibrary.wiley.com/doi/10.1111/2041-210X.12105/abstract>)
- Wood, S.N. 2006. *Generalized Additive Models: An Introduction with R*. CRC/Chapman & Hall.

## Examples

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function and look at the summary
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)
summary(hr.model)

# fit a simple smooth of x and y to counts
mod1 <- dsm(counts(x,y), hr.model, segdata, obsdata)
summary(mod1)

# predict over a grid
mod1.pred <- predict(mod1, preddata, preddata$area)

# calculate the predicted abundance over the grid
sum(mod1.pred)

# plot the smooth
plot(mod1)

## End(Not run)
```

---

 dsm-data

*Data format for DSM*


---

## Description

Two data.frames must be provided to `dsm`. They are referred to as `observation.data` and `segment.data`.

## Details

The `segment.data` table has the sample identifiers which define the segments, the corresponding effort (line length) expended and the environmental covariates that will be used to model abundance/density. `observation.data` provides a link table between the observations used in the detection function and the samples (segments), so that we can aggregate the observations to the segments (i.e. `observation.data` is a "look-up table" between the observations and the segments).

`observation.data` - the observation data.frame must have (at least) the following columns:

<code>object</code>	unique object identifier
<code>Sample.Label</code>	the identifier for the segment that the observation occurred in
<code>size</code>	the size of each observed group (e.g 1 if all animals occurred individually)
<code>distance</code>	distance to observation

One can often also use `observation.data` to fit a detection function (so additional columns for detection function covariates are allowed in this table).

`segment.data`: the segment data.frame must have (at least) the following columns:

<code>Effort</code>	the effort (in terms of length of the segment)
<code>Sample.Label</code>	identifier for the segment (unique!)
<code>???</code>	environmental covariates, for example location (projected latitude and longitude), and other relevant covariates

---

dsm.cor

*Check for autocorrelation in residuals*

---

## Description

Once a DSM has been fitted to data, this function can be used to check for autocorrelation in the residuals.

## Usage

```
dsm.cor(dsm.obj, Transect.Label = "Transect.Label",
        Segment.Label = "Segment.Label", max.lag = 10,
        resid.type = "scaled.pearson", fun = cor, ylim = c(0, 1),
        subset = "all", ...)
```

## Arguments

<code>dsm.obj</code>	a fitted dsm object.
<code>Transect.Label</code>	label for the transect (default: <code>Transect.Label</code> ). Using different labels can be useful when transects are split over geographical features or when transects are surveyed multiple times.
<code>Segment.Label</code>	label for the segments (default: <code>Segment.Label</code> ).The result of calling <code>order()</code> must make sense.
<code>max.lag</code>	maximum lag to calculate at.
<code>resid.type</code>	the type of residuals used, see <a href="#">residuals.gam</a> and <a href="#">residuals.gam</a> . Defaults to "scaled.pearson" in the GAM case and "normalized" in the GAMM case (which are equivalent).
<code>fun</code>	the function to use, by default <code>cor</code> , must take two column vectors as arguments.
<code>ylim</code>	user defined limits in y direction.
<code>subset</code>	which subset of the data should the correlation function be calculated on?
<code>...</code>	other options to pass to plot.

## Value

a plot or a vector of fun applied at the lags.



## Details

Within each `Transect.Label`, segments will be sorted according to their `Segment.Labels`. This may require some time to get right for your particular data. If one has multiple surveys where transects are revisited, for example, one may want to make `Transect.Label` a unique transect-survey id. Neither label need to be included in the model, they must just be present in the `$data` field in the model. This usually means that they have to be in the segment data passed to `dsm`.

The current iteration of this function will only plot correlations nicely, other things are up to you but you can get the function to return the data (by assigning the result to an object).

If there are NA values in the residuals then the correlogram will not be calculated. This usually occurs due to NA values in the covariates (so the smoother will not have fitted values there). Code like `'any(is.na(dsm.obj$data))'` might be helpful.

## Author(s)

David L. Miller

## Examples

```
library(Distance)
library(dsm)

# load the data, see ?mexdolphins
data(mexdolphins)

# fit a model
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)
mod1 <- dsm(count~s(x,y), hr.model, segdata, obsdata)

# look at lag 1 differences up to a maximum of lag 9, using deviance
# residuals
dsm.cor(mod1, resid.type="deviance", max.lag=9,
        Segment.Label="Sample.Label")
```

---

dsm.var.gam

*Prediction variance estimation assuming independence*

---

## Description

If one is willing to assume the the detection function and spatial model are independent, this function will produce estimates of variance of predictions of abundance, using the result that squared coefficients of variation will add.

## Usage

```
dsm.var.gam(dsm.obj, pred.data, off.set, seglen.varname = "Effort",
            type.pred = "response")
```

**Arguments**

dsm.obj	a model object returned from running <code>dsm</code> .
pred.data	either: a single prediction grid or list of prediction grids. Each grid should be a <code>data.frame</code> with the same columns as the original data.
off.set	a a vector or list of vectors with as many elements as there are in <code>pred.data</code> . Each vector is as long as the number of rows in the corresponding element of <code>pred.data</code> . These give the area associated with each prediction cell. If a single number is supplied it will be replicated for the length of <code>pred.data</code> .
seglen.varname	name for the column which holds the segment length (default value "Effort").
type.pred	should the predictions be on the "response" or "link" scale? (default "response").

**Details**

This is based on `dsm.var.prop` taken from code by Mark Bravington and Sharon Hedley.

**Value**

a list with elements

model	the fitted model object
pred.var	variance of the regions given in <code>pred.data</code> .
bootstrap	logical, always FALSE
model	the fitted model with the extra term
dsm.object	the original model, as above

**Author(s)**

David L. Miller

**Examples**

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function and look at the summary
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)
summary(hr.model)

# fit a simple smooth of x and y
mod1 <- dsm(count~s(x, y), hr.model, segdata, obsdata)

# Calculate the variance
# this will give a summary over the whole area in mexdolphins$preddata
mod1.var <- dsm.var.gam(mod1, preddata, off.set=preddata$area)
```

```
## End(Not run)
```

---

dsm.var.movblk                      *Variance estimation via parametric moving block bootstrap*

---

## Description

Estimate the variance in abundance over an area using a moving block bootstrap. Two procedures are implemented, one incorporating detection function uncertainty, one not.

## Usage

```
dsm.var.movblk(dsm.object, pred.data, n.boot, block.size, off.set,
  ds.uncertainty = FALSE, samp.unit.name = "Transect.Label",
  progress.file = NULL, bs.file = NULL, bar = TRUE)
```

## Arguments

dsm.object	object returned from <a href="#">dsm</a> .
pred.data	either: a single prediction grid or list of prediction grids. Each grid should be a <code>data.frame</code> with the same columns as the original data.
n.boot	number of bootstrap resamples.
block.size	number of segments in each block.
off.set	a a vector or list of vectors with as many elements as there are in <code>pred.data</code> . Each vector is as long as the number of rows in the corresponding element of <code>pred.data</code> . These give the area associated with each prediction cell. If a single number is supplied it will be replicated for the length of <code>pred.data</code> .
ds.uncertainty	incorporate uncertainty in the detection function? See Details, below. Note that this feature is EXPERIMENTAL at the moment.
samp.unit.name	name sampling unit to resample (default 'Transect.Label').
progress.file	path to a file to be used (usually by <code>Distance</code> ) to generate a progress bar (default NULL – no file written).
bs.file	path to a file to store each bootstrap round. This stores all of the bootstrap results rather than just the summaries, enabling outliers to be detected and removed. (Default NULL).
bar	should a progress bar be printed to screen? (Default TRUE).

## Details

Setting `ds.uncertainty=TRUE` will incorporate detection function uncertainty directly into the bootstrap. This is done by generating observations from the fitted detection function and then re-fitting a new detection function (of the same form), then calculating a new effective strip width. Rejection sampling is used to generate the observations (except in the half-normal case) so the procedure can be rather slow. Note that this is currently not supported with covariates in the detection function.

Setting `ds.uncertainty=FALSE` will incorporate detection function uncertainty using the delta method. This assumes that the detection function and the spatial model are INDEPENDENT. This is probably not reasonable.

## Examples

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function and look at the summary
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)
summary(hr.model)

# fit a simple smooth of x and y
mod1 <- dsm(count~s(x, y), hr.model, segdata, obsdata)
summary(mod1)

# calculate the variance by 500 moving block bootstraps
mod1.movblk <- dsm.var.movblk(mod1, preddata, n.boot = 500,
                             block.size = 3, samp.unit.name = "Transect.Label",
                             off.set = preddata$area,
                             bar = TRUE, bs.file = "mexico-bs.csv", ds.uncertainty = TRUE)

## End(Not run)
```

---

dsm.var.prop

*Prediction variance propagation for DSMs*

---

## Description

To ensure that uncertainty from the detection function is correctly propagated to the final variance estimate of abundance, this function uses a method first detailed in Williams et al (2011).

## Usage

```
dsm.var.prop(dsm.obj, pred.data, off.set, seglen.varname = "Effort",
            type.pred = "response")
```

**Arguments**

dsm.obj	a model object returned from running <code>dsm</code> .
pred.data	either: a single prediction grid or list of prediction grids. Each grid should be a <code>data.frame</code> with the same columns as the original data.
off.set	a a vector or list of vectors with as many elements as there are in <code>pred.data</code> . Each vector is as long as the number of rows in the corresponding element of <code>pred.data</code> . These give the area associated with each prediction cell. If a single number is supplied it will be replicated for the length of <code>pred.data</code> .
seglen.varname	name for the column which holds the segment length (default value "Effort").
type.pred	should the predictions be on the "response" or "link" scale? (default "response").

**Details**

The idea is to refit the spatial model but including an extra random effect. This random effect has zero mean and hence to effect on point estimates. Its variance is the Hessian of the detection function. Variance estimates then incorporate detection function uncertainty. Further mathematical details are given in the paper in the references below.

Many prediction grids can be supplied by supplying a list of `data.frames` to the function.

Note that this routine simply calls `dsm_varprop`. If you don't require multiple prediction grids, the other routine will probably be faster.

**Value**

a list with elements

model	the fitted model object
pred.var	variance of each region given in <code>pred.data</code> .
bootstrap	logical, always FALSE
pred.data	as above
off.set	as above
model	the fitted model with the extra term
dsm.object	the original model, as above
model.check	simple check of subtracting the coefficients of the two models to see if there is a large difference
deriv	numerically calculated Hessian of the offset

**Diagnostics**

The summary output from the function includes a simply diagnostic that shows the average probability of detection from the "original" fitted model (the model supplied to this function; column `Fitted.model`) and the probability of detection from the refitted model (used for variance propagation; column `Refitted.model`) along with the standard error of the probability of detection from the fitted model (`Fitted.model.se`), at the unique values of any covariates used in the detection function. If there are large differences between the probabilities of detection then there are potentially problems with the fitted model, the variance propagation or both. This can be because the fitted model does not account for enough of the variability in the data and in refitting the variance model accounts for this in the random effect.

**Limitations**

Note that this routine is only useful if a detection function has been used in the DSM. It cannot be used when the `Nhat`, `abundance.est` responses are used. Importantly this requires that if the detection function has covariates, then these do not vary within a segment (so, for example covariates like sex cannot be used).

Negative binomial models fitted using the `nb` family will give strange results (overly big variance estimates due to scale parameter issues) so `nb` models are automatically refitted with `negbin` (with a warning). It is probably worth refitting these models with `negbin` manually (perhaps giving a smallish range of possible values for the negative binomial parameter) to check that convergence was reached.

**Author(s)**

Mark V. Bravington, Sharon L. Hedley. Bugs added by David L. Miller.

**References**

Williams, R., Hedley, S.L., Branch, T.A., Bravington, M.V., Zerbini, A.N. and Findlay, K.P. (2011). Chilean Blue Whales as a Case Study to Illustrate Methods to Estimate Abundance and Evaluate Conservation Status of Rare Species. *Conservation Biology* 25(3), 526-535.

**Examples**

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function
df <- ds(distdata, max(distdata$distance),
        key = "hn", adjustment = NULL)

# fit a simple smooth of x and y
mod1 <- dsm(count~s(x, y), df, segdata, obsdata, family=tw())

# Calculate the variance
# this will give a summary over the whole area in mexdolphins$preddata
mod1.var <- dsm.var.prop(mod1, preddata, off.set=preddata$area)
summary(mod1.var)

## End(Not run)
```

---

dsm_varprop	<i>Variance propagation for density surface models</i>
-------------	--

---

**Description**

Calculate the uncertainty in predictions from a fitted DSM, including uncertainty from the detection function.

**Usage**

```
dsm_varprop(model, newdata, trace = FALSE, var_type = "Vp")
```

**Arguments**

model	a fitted <a href="#">dsm</a>
newdata	the prediction grid
trace	for debugging, see how the scale parameter estimation is going
var_type	which variance-covariance matrix should be used ("Vp" for variance-covariance conditional on smoothing parameter(s), "Vc" for unconditional). See <a href="#">gamObject</a> for an details/explanation. If in doubt, stick with the default, "Vp".

**Details**

When we make predictions from a spatial model, we also want to know the uncertainty about that abundance estimate. Since density surface models are 2 (or more) stage models, we need to incorporate the uncertainty from the earlier stages (i.e. the detection function) into our "final" uncertainty estimate.

This function will refit the spatial model but include the Hessian of the offset as an extra term. Variance estimates using this new model can then be used to calculate the variance of predicted abundance estimates which incorporate detection function uncertainty. Importantly this requires that if the detection function has covariates, then these do not vary within a segment (so, for example covariates like sex cannot be used).

For more information on how to construct the prediction grid data.frame, newdata, see [predict.dsm](#).

This routine is only useful if a detection function has been used in the DSM.

Note that we can use var\_type="Vc" here (see [gamObject](#)), which is the variance-covariance matrix for the spatial model, corrected for smoothing parameter uncertainty. See Wood, Pya & Svanfken (2016) for more information.

Negative binomial models fitted using the [nb](#) family will give strange results (overly big variance estimates due to scale parameter issues) so nb models are automatically refitted with [negbin](#) (with a warning). It is probably worth refitting these models with negbin manually (perhaps giving a smallish range of possible values for the negative binomial parameter) to check that convergence was reached.

**Value**

a list with elements

old_model	fitted model supplied to the function as model
refit	refitted model object, with extra term
pred	point estimates of predictions at newdata
var	total variance calculated over all of newdata
ses	standard error for each prediction cell in newdata

## Diagnostics

The summary output from the function includes a simple diagnostic that shows the average probability of detection from the "original" fitted model (the model supplied to this function; column `Fitted.model`) and the probability of detection from the refitted model (used for variance propagation; column `Refitted.model`) along with the standard error of the probability of detection from the fitted model (`Fitted.model.se`), at the unique values of any covariates used in the detection function. If there are large differences between the probabilities of detection then there are potentially problems with the fitted model, the variance propagation or both. This can be because the fitted model does not account for enough of the variability in the data and in refitting the variance model accounts for this in the random effect.

## Author(s)

David L. Miller, based on code from Mark V. Bravington and Sharon L. Hedley.

## References

Williams, R., Hedley, S.L., Branch, T.A., Bravington, M.V., Zerbini, A.N. and Findlay, K.P. (2011). Chilean Blue Whales as a Case Study to Illustrate Methods to Estimate Abundance and Evaluate Conservation Status of Rare Species. *Conservation Biology* 25(3), 526-535. Wood, S.N., Pya, N. and Svanbäck, B. (2016) Smoothing parameter and model selection for general smooth models. *Journal of the American Statistical Association*, 1-45.

## Examples

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function
df <- ds(distdata, max(distdata$distance),
        key = "hn", adjustment = NULL)

# fit a simple smooth of x and y
mod1 <- dsm(count~s(x, y), df, segdata, obsdata, family=tw())

# Calculate the variance
preddata$off.set <- preddata$area
mod1.varp <- dsm_varprop(mod1, preddata)
summary(mod1.varp)
```



```
# this will give a summary over the whole area in mexdolphins$preddata
## End(Not run)
```

---

```
generate.ds.uncertainty
```

*Generate data from a fitted detection function*

---

### Description

When ds.uncertainty is TRUE, this procedure generates data from the fitted detection function (assuming that it is correct).

### Usage

```
generate.ds.uncertainty(ds.object)
```

### Arguments

ds.object      a fitted detection function object (as returned by a call to ddf.ds()).

### Note

This function changes the random number generator seed. To avoid any potential side-effects, use something like: seed <- get(".Random.seed",envir=.GlobalEnv) before running code and assign(".Random.seed",seed,envir=.GlobalEnv) after.

### Author(s)

David L. Miller

---

```
generate.mb.sample      Moving block bootstrap sampler
```

---

### Description

Not usually used on its own, called from within `dsm.var.movblk`.

### Usage

```
generate.mb.sample(num.blocks.required, block.size, which.blocks, dsm.data,
  unit.info, n.units)
```

**Arguments**

num.blocks.required	number of blocks that we need.
block.size	number of segments per block.
which.blocks	which blocks should be sampled.
dsm.data	the \$data element of the result of a call to dsm.
unit.info	result of calling <a href="#">block.info.per.su</a> .
n.units	number of sampling units.

**Value**

vector of log-residuals

---

latlong2km

*Convert latitude and longitude to Northings and Eastings*

---

**Description**

Convert longitude and latitude co-ordinates to kilometres west-east and south-north from axes through (lon0,lat0) using the "spherical law of cosines".

**Usage**

```
latlong2km(lon, lat, lon0 = sum(range(lon))/2, lat0 = sum(range(lat))/2)
```

**Arguments**

lon	longitude
lat	latitude
lon0	longitude reference point (defaults to mean longitude)
lat0	latitude reference point (defaults to mean latitude)

**Details**

**WARNING:** This is an approximate procedure for converting between latitude/ longitude and Northing/Easting. Consider using projection conversions available in packages `sp` and `rgdal` for better results.

**Value**

list with elements `km.e` and `km.n`.

**Author(s)**

Simon N. Wood

---

`make.soapgrid`*Create a knot grid for the internal part of a soap film smoother.*

---

**Description**

This routine simply creates a grid of knots (in the correct format) to be used as in the "internal" part of the soap film smoother

**Usage**`make.soapgrid(bnd, n.grid)`**Arguments**

<code>bnd</code>	list with elements <code>x</code> and <code>y</code> which give the locations of the boundary vertices. The first and last elements should be the same.
<code>n.grid</code>	either one number giving the number of points along the <code>x</code> and <code>y</code> axes that should be used to create the grid, or a vector giving the number in the <code>x</code> direction, then <code>y</code> direction.

**Value**

a list with elements `x` and `y`, containing the knot locations.

**Author(s)**

David L Miller

---

`matrixnotposdef.handler`*Handler to suppress the "matrix not positive definite" warning*

---

**Description**

Internal function to suppress an annoying warnings from `chol()`

**Usage**`matrixnotposdef.handler(w)`**Arguments**

<code>w</code>	a warning
----------------	-----------

**Details**

See: <https://stat.ethz.ch/pipermail/r-help/2012-February/302407.html> See: <http://romainfrancois.blog.free.fr/index.php?post/specific-warnings>

**Value**

not a warning if the warning was "matrix not positive definite" or "the matrix is either rank-deficient or indefinite"

**Author(s)**

David L. Miller

---

mexdolphins

*Pan-tropical spotted dolphins in the Gulf of Mexico*

---

**Description**

Data from a combination of several NOAA shipboard surveys conducted on pan-tropical spotted dolphins in the Gulf of Mexico. 47 observations of groups of dolphins The group size was recorded, as well as the Beaufort sea state at the time of the observation. Coordinates for each observation and bathymetry data were also available as covariates for the analysis. A complete example analysis (and description of the data) is provided at <http://distancesampling.org/R/vignettes/mexico-analysis.html>.

**References**

Halpin, P.N., A.J. Read, E. Fujioka, B.D. Best, B. Donnelly, L.J. Hazen, C. Kot, K. Urian, E. LaBrecque, A. Dimatteo, J. Cleary, C. Good, L.B. Crowder, and K.D. Hyrenbach. 2009. OBIS-SEAMAP: The world data center for marine mammal, sea bird, and sea turtle distributions. *Oceanography* 22(2):104-115

NOAA Southeast Fisheries Science Center. 1996. Report of a Cetacean Survey of Oceanic and Selected Continental Shelf Waters of the Northern Gulf of Mexico aboard NOAA Ship Oregon II (Cruise 220)

---

offsets

*Offsets*

---

**Description**

This will be documentation on calculating offsets.

---

plot.dsm	<i>Plot a density surface model.</i>
----------	--------------------------------------

---

**Description**

See [plot.gam](#).

**Usage**

```
## S3 method for class 'dsm'  
plot(x, ...)
```

**Arguments**

x	a dsm object
...	other arguments passed to <a href="#">plot.gam</a> .

**Value**

a plot!

**Author(s)**

David L. Miller

**See Also**

dsm plot.gam

---

plot.dsm.var	<i>Create plots of abundance uncertainty</i>
--------------	--

---

**Description**

Note that the prediction data set must have x and y columns even if these were not used in the model.

**Usage**

```
## S3 method for class 'dsm.var'  
plot(x, poly = NULL, limits = NULL, breaks = NULL,  
      legend.breaks = NULL, xlab = "x", ylab = "y", observations = TRUE,  
      plot = TRUE, boxplot.coef = 1.5, x.name = "x", y.name = "y",  
      gg.grad = NULL, ...)
```

**Arguments**

x	a <code>dsm.var</code> object
poly	a <code>list</code> or <code>data.frame</code> with columns <code>x</code> and <code>y</code> , which gives the coordinates of a polygon to draw. It may also optionally have a column <code>group</code> , if there are many polygons.
limits	limits for the fill colours
breaks	breaks for the colour fill
legend.breaks	breaks as they should be displayed
xlab	label for the x axis
ylab	label for the y axis
observations	should observations be plotted?
plot	actually plot the map, or just return a <code>ggplot2</code> object?
boxplot.coef	control trimming (as in <code>summary.dsm.var</code> ), only has an effect if the bootstrap file was saved.
x.name	name of the variable to plot as the x axis.
y.name	name of the variable to plot as the y axis.
gg.grad	optional <code>ggplot</code> gradient object.
...	any other arguments

**Value**

a plot

**Details**

In order to get plotting to work with `dsm.var.prop` and `dsm.var.gam`, one must first format the data correctly since these functions are designed to compute very general summaries. One summary is calculated for each element of the list `pred` supplied to `dsm.var.prop` and `dsm.var.gam`.

For a plot of uncertainty over a prediction grid, `pred` (a `data.frame`), say, we can create the correct format by simply using `pred.new <- split(pred, 1:nrow(pred))`.

**Author(s)**

David L. Miller

**See Also**

`dsm.var.prop`, `dsm.var.gam`, `dsm.var.movblk`

---

plot_pred_by_term	<i>Spatially plot predictions per model term</i>
-------------------	--

---

### Description

Plot the effect of each smooth in the model spatially. For each term in the model, plot its effect in space. Plots are made on the same scale, so that the relative influence of each smooth can be seen.

### Usage

```
plot_pred_by_term(dsm.obj, data, location_cov = c("x", "y"))
```

### Arguments

dsm.obj	fitted dsm object
data	data to use to plot (often the same as the precision grid), data should also include width and height columns for plotting
location_cov	which covariates to plot by (usually 2, spatial covariates, by default =c("x", "y"))

### Value

a ggplot2 plot

### Author(s)

David L Miller (idea taken from inlabru)

### Examples

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data and fit a model
data(mexdolphins)
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)
mod1 <- dsm(count~s(x,y) + s(depth), hr.model, segdata, obsdata)

preddata$width <- preddata$height <- sqrt(preddata$area)

# make the plot
plot_pred_by_term(mod1, preddata, c("x", "y"))

# better plot would be
# library(viridis)
# plot_pred_by_term(mod1, preddata, c("x", "y")) + scale_fill_viridis()

## End(Not run)
```

---

`predict.dsm`*Predict from a fitted density surface model*

---

**Description**

Make predictions outside (or inside) the covered area.

**Usage**

```
## S3 method for class 'dsm'  
predict(object, newdata = NULL, off.set = NULL,  
        type = "response", ...)
```

**Arguments**

<code>object</code>	a fitted <a href="#">dsm</a> object as produced by <code>dsm()</code> .
<code>newdata</code>	spatially referenced covariates e.g. altitude, depth, distance to shore, etc. Covariates in the <code>data.frame</code> must have names <i>*identical*</i> to variable names used in fitting the DSM.
<code>off.set</code>	area of each of the cells in the prediction grid. Should be in the same units as the segments/distances given to <code>dsm</code> . Ignored if there is already a column in <code>newdata</code> called <code>off.set</code> .
<code>type</code>	what scale should the results be on. The default is "response", see <a href="#">predict.gam</a> for an explanation of other options (usually not necessary).
<code>...</code>	any other arguments passed to <a href="#">predict.gam</a> .

**Details**

If `newdata` is not supplied, predictions are made for the data that built the model. Note that the order of the results will not necessarily be the same as the `segdata` (segment data) `data.frame` that was supplied (it will be sorted by the `Segment.Label` field).

**Value**

predicted values on the response scale (density/abundance).

**Author(s)**

David L. Miller

**See Also**

[predict.gam](#) [dsm.var.gam](#) [dsm.var.prop](#) [dsm.var.movblk](#)



---

print.dsm	<i>Print a description of a density surface model object</i>
-----------	--

---

**Description**

This method just gives a short description of the fitted model. Use the [summary.dsm](#) method for more information.

**Usage**

```
## S3 method for class 'dsm'  
print(x, ...)
```

**Arguments**

x	a dsm object
...	unspecified and unused arguments for S3 consistency

**Author(s)**

David L. Miller

**See Also**

[summary.ds](#)

---

print.dsm.var	<i>Print a description of a density surface model variance object</i>
---------------	---

---

**Description**

This method only provides a short summary, use the [summary.dsm.var](#) method for information.

**Usage**

```
## S3 method for class 'dsm.var'  
print(x, ...)
```

**Arguments**

x	a dsm variance object
...	unspecified and unused arguments for S3 consistency

**Author(s)**

David L. Miller

**See Also**

[summary.dsm.var](#)

---

`print.dsm_varprop`      *Print a description of a density surface model variance object*

---

**Description**

This method only provides a short summary, see [summary.dsm\\_varprop](#).

**Usage**

```
## S3 method for class 'dsm_varprop'  
print(x, ...)
```

**Arguments**

`x`                    a dsm variance object  
`...`                unspecified and unused arguments for S3 consistency

**Author(s)**

David L. Miller

**See Also**

[summary.dsm\\_varprop](#)

---

`print.summary.dsm.var`      *Print summary of density surface model variance object*

---

**Description**

See [summary.dsm.var](#) for information.

**Usage**

```
## S3 method for class 'summary.dsm.var'  
print(x, ...)
```

**Arguments**

`x`                    a summary of dsm variance object  
`...`                unspecified and unused arguments for S3 consistency

**Author(s)**

David L. Miller

**See Also**

[summary.dsm.var](#)

---

`print.summary.dsm_varprop`

*Print summary of density surface model variance object*

---

**Description**

See [summary.dsm\\_varprop](#) for information.

**Usage**

```
## S3 method for class 'summary.dsm_varprop'  
print(x, ...)
```

**Arguments**

`x` a summary of dsm variance object  
`...` unspecified and unused arguments for S3 consistency

**Author(s)**

David L. Miller

**See Also**

[summary.dsm.var](#)

---

`rqgam.check`

*Randomised quantile residuals check plot for GAMs/DSMs*

---

**Description**

Reproduces the "Resids vs. linear pred" plot from [gam.check](#) but using randomised quantile residuals, a la Dunn and Smyth (1996). Checks for heteroskedasticity as usual, looking for "funnel"-type structures in the points, which is much easier with randomised quantile residuals than with deviance residuals, when your model uses a count distribution as the response.

**Usage**

```
rqgam.check(gam.obj, ...)
```

**Arguments**

gam.obj            a gam, glm or dsm object.  
 ...                arguments passed on to all plotting functions

**Details**

Note that this function only works with negative binomial and Tweedie response distributions.

Earlier versions of this function produced the full gam.check output, but this was confusing as only one of the plots was really usedul. Checks of k are not computed, these need to be done using [gam.check](#).

**Value**

just plots!

**Author(s)**

Based on code provided by Natalie Kelly, bugs added by Dave Miller

**Examples**

```
library(Distance)
library(dsm)
library(tweedie)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function and look at the summary
hr.model <- ds(distdata, max(distdata$distance),
               key = "hr", adjustment = NULL)

# fit a simple smooth of x and y with a Tweedie response with estimated
# p parameter
mod1 <- dsm(count~s(x, y), hr.model, segdata, obsdata, family=tw())
rqgam.check(mod1)
```

---

summary.dsm

*Summarize a fitted density surface model*

---

**Description**

Gives a brief summary of a fitted dsm object.

**Usage**

```
## S3 method for class 'dsm'
summary(object, ...)
```

**Arguments**

object            a dsm object  
 ...              other arguments passed to [summary.gam](#).

**Value**

a summary object

**Author(s)**

David L. Miller

**See Also**

dsm

---

summary.dsm.var

*Summarize the variance of a density surface model*

---

**Description**

Gives a brief summary of a fitted dsm variance object.

**Usage**

```
## S3 method for class 'dsm.var'
summary(object, alpha = 0.05, boxplot.coef = 1.5,
        bootstrap.subregions = NULL, ...)
```

**Arguments**

object            a dsm.var object  
 alpha            alpha level for confidence intervals (default 0.05 to give a 95% confidence interval, i.e. we generate  $100 \times c(\alpha/2, 1-\alpha/2)$  confidence intervals)  
 boxplot.coef    the value of coef used to calculate the outliers see [boxplot](#).  
 bootstrap.subregions  
                  list of vectors of logicals or indices for subregions for which variances need to be calculated (only for bootstraps (see [dsm.var.prop](#) for how to use subregions with variance propagation).  
 ...              unused arguments for S3 compatibility

**Value**

a summary object

**Author(s)**

David L. Miller

**See Also**

dsm.var.movblk dsm.var.prop

---

summary.dsm\_varprop    *Summarize the variance of a density surface model*

---

**Description**

Gives a brief summary of a fitted dsm\_varprop variance object.

**Usage**

```
## S3 method for class 'dsm_varprop'  
summary(object, alpha = 0.05, ...)
```

**Arguments**

object	a dsm.var object
alpha	alpha level for confidence intervals (default 0.05 to give a 95% confidence interval)
...	unused arguments for S3 compatibility

**Value**

a summary object

**Author(s)**

David L. Miller

**See Also**

dsm\_varprop summary.dsm.var

---

trim.var	<i>Trimmed variance</i>
----------	-------------------------

---

**Description**

Trim the variance estimates from the bootstrap. This is defined as the percentage defined as amount necessary to bring median and trimmed mean within 8

**Usage**

```
trim.var(untrimmed.bootstraps, boxplot.coef = 1.5)
```

**Arguments**

untrimmed.bootstraps  
(usually the \$study.area.total element of a returned dsm bootstrap object.)

boxplot.coef the value of coef used to calculate the outliers see [boxplot](#).

**Details**

Code originally by Louise Burt.

**Value**

trimmed variance

**Author(s)**

Louise Burt

---

vis.concurvity	<i>Visualise concurvity between terms in a GAM</i>
----------------	--

---

**Description**

Plot measures of how much one term in the model could be explained by another. When values are high, one should consider re-running variable selection with one of the offending variables removed to check for stability in term selection.

**Usage**

```
vis.concurvity(model, type = "estimate")
```

**Arguments**

model fitted model

type concurvity measure to plot, see [concurvity](#)

**Details**

These methods are considered somewhat experimental at this time. Consult [concurvity](#) for more information on how concurvity measures are calculated.

**Author(s)**

David L Miller

**Examples**

```
## Not run:
library(Distance)
library(dsm)

# load the Gulf of Mexico dolphin data (see ?mexdolphins)
data(mexdolphins)

# fit a detection function and look at the summary
hr.model <- ds(distdata, max(distdata$distance),
              key = "hr", adjustment = NULL)

# fit a simple smooth of x and y to counts
mod1 <- dsm(count~s(x,y)+s(depth), hr.model, segdata, obsdata)

# visualise concurvity using the "estimate" metric
vis.concurvity(mod1)

## End(Not run)
```



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