

Package ‘xxIRT’

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Type Package

Title Item Response Theory and Computer-Based Testing in R

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Description A suite of practical psychometric analysis and research tools of item response theory, including the 3-parameter-logistic model and the generalized partial credit model as well as functions to perform: (1) parameter estimation, (2) automated test assembly, (3) simulation of computerized adaptive testing (CAT), and (4) assembly and simulation of multistage testing. More documentation at <<https://github.com/xluo11/xxIRT>>.

License GPL (>= 3)

Depends R (>= 3.1.0)

URL <https://github.com/xluo11/xxIRT>

BugReports <https://github.com/xluo11/xxIRT/issues>

Imports ggplot2, lpSolveAPI, reshape2, stats, utils

RoxygenNote 6.0.1

Suggests testthat

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```

ata_item_use(x, min = NA, max = NA, items = NULL)

ata_item_enemy(x, items)

ata_item_fixedvalue(x, items, min = NA, max = NA, forms = NULL,
  collapse = FALSE)

ata_solve(x, as.list = TRUE, timeout = 10, mip_gap = 0.1,
  verbose = "neutral", warning = FALSE, ...)

ata_solve_lpsolve(x, ...)

```

Arguments

pool	item pool (must include a, b, c parameters), a data.frame
num_form	the number of forms to be assembled
len	the length of each form
max_use	the maximum use of each item
group	the grouping indices
...	further arguments
x	the ata object
mat	the coefficient matrix
dir	direction
rhs	right-hand-side value
forms	the indices of forms where objectives are added. NULL for all forms
collapse	TRUE to collapse all forms into one objective function
coef	the coefficients of the objective function or the constraint
compensate	TRUE to combine coefficients
mode	the optimization mode: 'max' for maximization and 'min' for minimization
negative	TRUE when the expected value of the objective function is negative
flatten	the flatten parameter to make the objective function flat
target	the target of the objective function
min	the lower bound of the constraint
max	the upper bound of the constraint
level	the level value for categorical variable
items	a vector of item indices
as.list	TRUE to return results in a list; otherwise, data frame
timeout	the time limit in seconds
mip_gap	the mip gap parameter
verbose	the message parameter
warning	TRUE to output warning message when LP is not solved

Details

The `ata` object stores LP definitions in `obj`, `mat`, `dir`, `rhs`, `types`, `bounds`, `max`. When calling `ata_solve`, it converts these definitions to the real LP object. If solved successfully, two results are added to the object: `result` (a matrix of binary selection results) and `items` (a list or data frame of selected items).

To maximize the LP, it is to maximize y while subject to $\text{sum}(x) - y \geq 0$ and $\leq F$ (flatten parameter). To minimize the LP, it is to minimize y while subject to $\text{sum}(x) - y \leq 0$ and $\geq F$. By default, y is non-negative. When `negative=TRUE`, y is set to be negative.

When `coef` is a pool-size or form-size numeric vector, coefficients are used directly. When `coef` is a variable name, variable values are used as coefficients. When `coef` is a numeric vector unequal to pool size, information at those points are used as coefficients.

`ata_obj_absolute` is to minimize y while subject to $\text{sum}(x) + y \geq T$ and $\text{sum}(x) - y \leq T$.

For `ata_constraint`, set `coef` to a variable name and `level` a level of that variable to add a categorical constraint. Set `coef` to a variable name and leave `level` to default value (NULL or NA) to add a quantitative constraint. Set `coef` to a constant or a vector to add a constraint directly.

Examples

```
## Not run:
## generate a 100-item pool
nitems <- 100
pool <- with(model_3pl_gendata(1, nitems), data.frame(id=1:nitems, a=a, b=b, c=c))
pool$id <- 1:nitems
pool$content <- sample(1:3, nitems, replace=TRUE)
pool$time <- round(rlnorm(nitems, log(60), .2))
pool$group <- sort(sample(1:round(nitems/3), nitems, replace=TRUE))

## ex. 1: 6 forms, 10 items, maximize b parameter
x <- ata(pool, 6, len=10, max_use=1)
x <- ata_obj_relative(x, "b", "max")
x <- ata_solve(x, timeout=5)
sapply(x$items, function(x) summary(x$b))

## ex. 2: 3 forms, 10 items, minimize b parameter
x <- ata(pool, 3, len=10, max_use=1)
x <- ata_obj_relative(x, "b", "min", negative=TRUE)
x <- ata_solve(x, as.list=FALSE, timeout=5)
aggregate(x$items$b, by=list(form=x$items$form), summary)

## ex. 3: 2 forms, 10 items, mean(b) = 0, sd(b) = 1.0, content = (3, 3, 4)
x <- ata(pool, 2, len=10, max_use=1)
x <- ata_obj_absolute(x, pool$b, 0 * 10)
x <- ata_obj_absolute(x, (pool$b - 0)^2, 1 * 10)
x <- ata_constraint(x, "content", min=3, max=3, level=1)
x <- ata_constraint(x, "content", min=3, max=3, level=2)
x <- ata_constraint(x, "content", min=4, max=4, level=3)
x <- ata_solve(x, timeout=5)
sapply(x$items, function(x) c(mean=mean(x$b), sd=sd(x$b)))

## ex. 4: same with ex. 3, but group-based
```

```

x <- ata(pool, 2, len=10, max_use=1, group="group")
x <- ata_obj_absolute(x, pool$b, 0 * 10)
x <- ata_obj_absolute(x, (pool$b - 0)^2, 1 * 10)
x <- ata_constraint(x, "content", min=3, max=3, level=1)
x <- ata_constraint(x, "content", min=3, max=3, level=2)
x <- ata_constraint(x, "content", min=4, max=4, level=3)
x <- ata_solve(x, timeout=5)
sapply(x$items, function(x) c(mean=mean(x$b), sd=sd(x$b),
                             n_items=length(unique(x$id)), n_groups=length(unique(x$group))))

# ex. 5: 2 forms, 10 items, flat TIF over [-1, 1]
x <- ata(pool, 2, len=10, max_use=1)
x <- ata_obj_relative(x, seq(-1, 1, .5), "max", flatten=0.05)
x <- ata_solve(x)
plot(x)

## End(Not run)

```

cat_sim

*Simulation of Computerized Adaptive Testing (CAT)***Description**

Simulation of Computerized Adaptive Testing (CAT)

cat_sim uns a simulation of CAT. Use theta in options to set the starting value of theta estimate.

cat_estimate_mle is the maximum likelihood estimation rule. Use map_len to apply MAP to the first K items and use map_prior to set the prior for MAP.

cat_estimate_eap is the expected a posteriori estimation rule, using eap_mean and eap_sd option parameters as the prior

cat_estimate_hybrid is a hybrid estimation rule, which uses MLE for mixed responses and EAP for all 1's or 0's responses

cat_stop_default is a three-way stopping rule. When stop_se is set in the options, it uses the standard error stopping rule. When stop_mi is set in the options, it uses the minimum information stopping rule. When stop_cut is set in the options, it uses the confidence interval (set by ci_width) stopping rule.

cat_select_maxinfo is the maximum information selection rule. Use group (a numeric vector) to group items belonging to the same set. Use info_random to implement the random-esque item exposure control method.

cat_select_ccat is the constrained CAT selection rule. Use ccat_var to set the content variable in the pool. Use ccat_perc to set the desired content distribution, with the name of each element being the content code and tue value of each element being the percentage. Use ccat_random to add randomness to initial item selections.

cat_select_shadow is the shadow-test selection rule. Use shadow_id to group item sets. Use constraints to set constraints. Constraints should be in a data.frame with four columns: var (variable name), level (variable level, NA for quantitative variable), min (lower bound), and max (upper bound).

cat_stop_projection is the projection-based stopping rule. Use projection_method to choose the projection method ('info' or 'diff'). Use stop_cut to set the cut score. Use constraints to set the constraints. Constraints should be a data.frame with columns: var (variable name), level (variable level, NA for quantitative variable), min (lower bound), max (upper bound)

Usage

```
cat_sim(true, pool, ...)

cat_estimate_mle(len, theta, stats, admin, pool, opts)

cat_estimate_eap(len, theta, stats, admin, pool, opts)

cat_estimate_hybrid(len, theta, stats, admin, pool, opts)

cat_stop_default(len, theta, stats, admin, pool, opts)

cat_select_maxinfo(len, theta, stats, admin, pool, opts)

cat_select_ccat(len, theta, stats, admin, pool, opts)

cat_select_shadow(len, theta, stats, admin, pool, opts)

## S3 method for class 'cat'
print(x, ...)

## S3 method for class 'cat'
plot(x, ...)

cat_stop_projection(len, theta, stats, admin, pool, opts)
```

Arguments

true	the true theta
pool	the item pool (data.frame)
...	option/control parameters
len	the current test length
theta	the current theta estimate
stats	a matrix of responses, theta estimate, information and std error
admin	a data frame of administered items
opts	a list of option/control parameters
x	a cat object

Details

... takes a variety of option/control parameters for the simulations from users. min and max are mandatory for setting limits on the test length. User-defined selection, estimation, and stopping

rules are also passed to the simulator via options.

To write a new rule, the function signature must be: `function(len, theta, stats, admin, pool, opts)`.

See built-in rules for examples.

Value

`cat_sim` returns a `cat` object

an estimation rule should return a theta estimate

a stopping rule should return a boolean: `TRUE` to stop the CAT, `FALSE` to continue

a selection rule should return a list of (a) the selected item and (b) the updated pool

Examples

```
## Not run:
## generate a 100-item pool
num_items <- 100
pool <- with(model_3pl_gendata(1, num_items), data.frame(a=a, b=b, c=c))
pool$set_id <- sample(1:30, num_items, replace=TRUE)
pool$content <- sample(1:3, num_items, replace=TRUE)
pool$time <- round(rlnorm(num_items, mean=4.1, sd=.2))

## MLE, EAP, and hybrid estimation rule
cat_sim(1.0, pool, min=10, max=20, estimate_rule=cat_estimate_mle)
cat_sim(1.0, pool, min=10, max=20, estimate_rule=cat_estimate_eap)
cat_sim(1.0, pool, min=10, max=20, estimate_rule=cat_estimate_hybrid)

## SE, MI, and CI stopping rule
cat_sim(1.0, pool, min=10, max=20, stop_se=.3)
cat_sim(1.0, pool, min=10, max=20, stop_mi=.6)
cat_sim(1.0, pool, min=10, max=20, stop_cut=0)
cat_sim(1.0, pool, min=10, max=20, stop_cut=0, ci_width=2.58)

## maximum information selection with item sets
cat_sim(1.0, pool, min=10, max=20, group="set_id")$admin

## maximum information with item exposure control
cat_sim(1.0, pool, min=10, max=20, info_random=5)$admin

## Constrained-CAT selection rule with and without initial randomness
cat_sim(1.0, pool, min=10, max=20, select_rule=cat_select_ccat,
        ccat_var="content", ccat_perc=c("1"=.2, "2"=.3, "3"=.5))
cat_sim(1.0, pool, min=10, max=20, select_rule=cat_select_ccat, ccat_random=5,
        ccat_var="content", ccat_perc=c("1"=.2, "2"=.3, "3"=.5))

## Shadow-test selection rule
cons <- data.frame(var='content', level=1:3, min=c(3,3,4), max=c(3,3,4))
cons <- rbind(cons, data.frame(var='time', level=NA, min=55*10, max=65*10))
cat_sim(1.0, pool, min=10, max=10, select_rule=cat_select_shadow, constraints=cons)

## Projection-based stopping rule
cons <- data.frame(var='content', level=1:3, min=5, max=15)
```

```

cons <- rbind(cons, data.frame(var='time', level=NA, min=60*20, max=60*40))
cat_sim(1.0, pool, min=20, max=40, select_rule=cat_select_shadow, stop_rule=cat_stop_projection,
        projection_method="diff", stop_cut=0, constraints=cons)

## End(Not run)

```

model_3pl

3-parameter-logistic model

Description

3-parameter-logistic model

model_3pl_prob computes the probability of a correct response for given parameters

model_3pl_info computes the information for given parameters

model_3pl_lik computes the likelihood of observed responses

model_3pl_rescale transforms parameters to a given scale

model_3pl_gendata generates data using the 3pl model

model_3pl_plot plots the item characteristics curve (ICC) or item information function curve (IIFC)

model_3pl_plot_loglik plots the log-likelihood curves for each response vector

model_3pl_jmle estimates parameters using the joint MLE method

model_3pl_mmle estimates parameters using the marginal MLE method

model_3pl_eap_scoring computes scores using the EAP method

Usage

```
model_3pl_prob(t, a, b, c, D = 1.702)
```

```
model_3pl_info(t, a, b, c, D = 1.702)
```

```
model_3pl_lik(u, t, a, b, c, D = 1.702, log = FALSE)
```

```
model_3pl_rescale(t, a, b, c, param = c("t", "b"), mean = 0, sd = 1)
```

```
model_3pl_gendata(num_people, num_item, t = NULL, a = NULL, b = NULL,
  c = NULL, D = 1.702, t_dist = c(0, 1), a_dist = c(0, 0.2),
  b_dist = c(0, 1), c_dist = c(5, 46), missing = NULL)
```

```
model_3pl_plot(a, b, c, D = 1.702, type = c("prob", "info"),
  total = FALSE, xaxis = seq(-4, 4, 0.1))
```

```
model_3pl_plot_loglik(u, a, b, c, D = 1.702, xaxis = seq(-4, 4, 0.1),
  show_mle = FALSE)
```



```

model_3pl_dv_t(u, t, a, b, c, D, prior = NULL)

model_3pl_dv_a(u, t, a, b, c, D, prior = NULL, post_prob = NULL)

model_3pl_dv_b(u, t, a, b, c, D, prior = NULL, post_prob = NULL)

model_3pl_dv_c(u, t, a, b, c, D, prior = NULL, post_prob = NULL)

model_3pl_estimate_inits(u, t, a, b, c)

model_3pl_estimate_nr(param, h, is_free, h_max, bounds)

model_3pl_jmle(u, t = NA, a = NA, b = NA, c = NA, D = 1.702,
  num_iter = 100, num_nr = 15, h_max = 1, conv = 0.1, decay = 0.95,
  scale = NULL, bounds = list(t = c(-4, 4), a = c(0.1, 2), b = c(-4, 4), c =
  c(0.01, 0.3)), priors = list(t = c(0, 1), a = c(0, 0.2), b = c(0, 1), c =
  c(5, 46)), debug = FALSE)

model_3pl_posterior_dist(u, a, b, c, D, quad_t, quad_w)

model_3pl_mmle(u, a = NA, b = NA, c = NA, D = 1.702, num_iter = 100,
  num_nr = 15, num_quad = c("11", "20"), h_max = 1, conv = 0.1,
  decay = 0.98, scale = NULL, bounds = list(t = c(-4, 4), a = c(0.1, 2), b
  = c(-4, 4), c = c(0.01, 0.3)), priors = list(t = c(0, 1), a = c(0, 0.2), b =
  c(0, 1), c = c(5, 46)), debug = FALSE)

model_3pl_eap_scoring(u, a, b, c, D)

```

Arguments

t	ability parameter, 1d vector
a	discrimination parameters, 1d vector
b	difficulty parameters, 1d vector
c	guessing parameters, 1d vector
D	the scaling constant, 1.702 by default
u	observed responses, 2d matrix
log	True to return log-likelihood
param	the parameter of the new scale, t or b
mean	the mean of the new scale
sd	the SD of the new scale
num_people	the number of people to be generated
num_item	the number of items to be generated
t_dist	the normal distribution parameters of t-parameters, a vector: c(mean, sd)
a_dist	the lognormal distribution parameters of a-parameters, a vector: c(meanlog, sd-log)

b_dist	the normal distribution parameters of b-parameters, a vector: c(mean, sd)
c_dist	the beta distribution parameters of c-parameters, a vector: c(alpha, beta)
missing	the proportion or number of missing responses
type	the type of plot, prob for ICC and info for IIFC
total	TRUE to sum values over items
xaxis	the values of x-axis
show_mle	TRUE to print maximum likelihood values
prior	parameters of the prior distribution
post_prob	posterior distribution of the theta
h	change of parameters in the newton-raphson method
is_free	TRUE to estimate parameters and FALSE to fix parameters
h_max	the maximum value of h in the newton-raphson method
bounds	the bounds of parameters, a list
num_iter	the maximum number of overall iterations
num_nr	the maximum number of the newton-raphson iterations
conv	the convergence criterion in -2 log-likelihood of model fit
decay	the epoch decay parameter
scale	the scale of theta parameters
priors	the priors of parameters used in the maximum a posteriori estimation
debug	TRUE to print debugging information
quad_t	values of quadrature points
quad_w	weights of quadrature points
num_quad	the number of quadrature points

Value

model_3pl_prob returns a 2d matrix of probabilities, dim = n_people x n_items
 model_3pl_info returns a 2d matrix of informations, dim = n_people x n_items
 model_3pl_lik returns a 2d matrix of likelihood, dim = n_people x n_items
 model_3pl_rescale returns a list of rescaled t, a, b, c parameters
 model_3pl_gendata returns a list of generated data
 model_3pl_plot returns a ggplot graph
 model_3pl_plot returns a ggplot graph
 model_3pl_jmle returns estimated parameters
 model_3pl_eap_scoring returns the EAP scores

Examples

```

model_3pl_prob(c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.702)
model_3pl_prob(c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.0)
model_3pl_info(c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.702)
model_3pl_info(c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.0)
u <- matrix(c(1, 0, 1, 0, 1, 0), nrow=2)
model_3pl_lik(u, c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.702, FALSE)
model_3pl_lik(u, c(-1, 1), c(1, .8, .8), c(-1, 1, 1), c(0, 0, .2), 1.0, TRUE)
model_3pl_gendata(10, 5)
model_3pl_gendata(10, 5, a=1, c=0, missing=.1)
with(model_3pl_gendata(10, 5), model_3pl_plot(a, b, c, type="prob"))
with(model_3pl_gendata(10, 5), model_3pl_plot(a, b, c, type="info", total=TRUE))
with(model_3pl_gendata(5, 50), model_3pl_plot_loglik(u, a, b, c, show_mle=TRUE))
## Not run:
data_tru <- model_3pl_gendata(3000, 50)
data_est <- model_3pl_jmle(u=data_tru$u, scale=c(0, 1), priors=NULL, debug=TRUE)
evaluate_3pl_estimation(data_tru, data_est)

## End(Not run)
## Not run:
data_tru <- model_3pl_gendata(3000, 50)
data_est <- model_3pl_mmle(u=data_tru$u, scale=NULL, priors=NULL, debug=TRUE)
evaluate_3pl_estimation(data_tru, data_est)

## End(Not run)

```

model_gpcm

Generalized partial credit model

Description

Generalized partial credit model

model_gpcm_prob computes the probability of all score categories

model_gpcm_info computes the informations of all score categories

model_gpcm_onehot_response converts 2-dimensional score matrix to a 3-dimensional one-hot vector of score category

model_gpcm_lik computes the (log-)likelihood of the responses

model_gpcm_gendata generates data using the GPCM model

model_gpcm_plot plots the item characteristics curve (ICC) or item information function curve (IIFC)

model_gpcm_plot_loglik plots the log-likelihood curves for each response vector

model_gpcm_jmle estimates the parameters using the joint MLE method

Usage

```

model_gpcm_prob(t, a, b, d, D = 1.702, add_initial = NULL)

model_gpcm_info(t, a, b, d, D = 1.702, add_initial = NULL)

model_gpcm_onehot_response(u, num_category = NULL)

model_gpcm_extract_3Ddata(data, u)

model_gpcm_lik(u, t, a, b, d, D = 1.702, add_initial = NULL, log = FALSE)

model_gpcm_gendata(num_people, num_item, num_category, sort_b = TRUE,
  t = NULL, a = NULL, b = NULL, D = 1.702, set_initial = NULL,
  t_dist = c(0, 1), a_dist = c(0, 0.2), b_dist = c(0, 1),
  missing = NULL)

model_gpcm_plot(a, b, d, D = 1.702, add_initial = NULL, type = c("prob",
  "info"), by_item = FALSE, total = FALSE, xaxis = seq(-6, 6, 0.1))

model_gpcm_plot_loglik(u, a, b, d, D = 1.702, add_initial = NULL,
  xaxis = seq(-6, 6, 0.1), show_mle = FALSE)

model_gpcm_dv_t(u, t, a, b, D, prior = NULL)

model_gpcm_dv_a(u, t, a, b, D, prior = NULL, post_prob = NULL)

model_gpcm_dv_b(u, t, a, b, D, prior = NULL, post_prob = NULL)

model_gpcm_estimate_inits(u, t, a, b, d, set_initial)

model_gpcm_estimate_nr(param, h, is_free, h_max, bounds)

model_gpcm_jmle(u, t = NA, a = NA, b = NA, d = NA, D = 1.702,
  set_initial = 0, num_iter = 100, num_nr = 15, h_max = 1, conv = 0.1,
  decay = 0.95, scale = NULL, bounds = list(t = c(-4, 4), a = c(0.1, 2), b
  = c(-4, 4)), priors = list(t = c(0, 1), a = c(0, 0.2), b = c(0, 1)),
  debug = FALSE)

```

Arguments

t	ability parameters, a vector
a	discrimination parameters, a vector
b	item location parameters when it's a matrix; item-category parameters when it's a vector
d	NULL or item category parameters
D	the scaling constant
add_initial	the initial value added to item category parameters

<code>u</code>	the observed scores (starting from 0), 2d matrix
<code>num_category</code>	the number of score categories
<code>data</code>	the 3-dimensional data
<code>log</code>	TRUE to return log-likelihood
<code>num_people</code>	the number of people to be generated
<code>num_item</code>	the number of items to be generated
<code>sort_b</code>	TRUE to sort b parameters of each item
<code>set_initial</code>	the value of the initial category
<code>t_dist</code>	the normal distribution parameters of t-parameters, a vector: c(mean, sd)
<code>a_dist</code>	the lognormal distribution parameters of a-parameters, a vector: c(meanlog, sd-log)
<code>b_dist</code>	the normal distribution parameters of b-parameters, a vector: c(mean, sd)
<code>missing</code>	the proportion or number of missing responses
<code>type</code>	the type of plot, prob for ICC and info for IIFC
<code>by_item</code>	TRUE to combine categories
<code>total</code>	TRUE to sum values over items
<code>xaxis</code>	the values of x-axis
<code>show_mle</code>	TRUE to print maximum likelihood values
<code>prior</code>	parameters of the prior distribution
<code>post_prob</code>	posterior distribution of the theta
<code>param</code>	the parameters to be updated
<code>h</code>	change of parameters in the newton-raphson method
<code>is_free</code>	TRUE to estimate parameters and FALSE to fix parameters
<code>h_max</code>	the maximum value of h in the newton-raphson method
<code>bounds</code>	the bounds of parameters, a list
<code>num_iter</code>	the maximum number of overall iterations
<code>num_nr</code>	the maximum number of the newton-raphson iterations
<code>conv</code>	the convergence criterion in -2 log-likelihood of model fit
<code>decay</code>	the epoch decay parameter
<code>scale</code>	the scale of theta parameters
<code>priors</code>	the priors of parameters used in the maximum a posteriori estimation
<code>debug</code>	TRUE to print debugging information

Details

The GPCM has two kinds of parameterization: (1) b as the item-category parameters or (2) b - d as the item-category parameters. In (1), b must be a matrix and d NULL. In (2), b must be a vector and d a matrix. Use NA to represent unused category. Use `initial` to insert the values of the initial category.

Value

`model_gpcm_gendata` returns a list of generated data

`model_gpcm_plot` returns a ggplot graph

`model_gpcm_plot` returns a ggplot graph

Examples

```

model_gpcm_gendata(10, 5, 3)
model_gpcm_gendata(10, 5, 3, set_initial=0, missing=.1)
# Figure 1 in Muraki, 1992 (APM)
model_gpcm_plot(a=c(1,1,.7), b=matrix(c(-2,0,2,-.5,0,2,-.5,0,2), nrow=3, byrow=TRUE),
  d=NULL, D=1.0, add_initial=0, xaxis=seq(-4, 4, .1), type='prob')
# Figure 2 in Muraki, 1992 (APM)
model_gpcm_plot(a=.7, b=matrix(c(.5,0,NA,0,0,0), nrow=2, byrow=TRUE),
  d=NULL, D=1.0, add_initial=0, xaxis=seq(-4, 4, .1))
# Figure 3 in Muraki, 1992 (APM)
model_gpcm_plot(a=c(.778,.946), b=matrix(c(1.759,-1.643,3.970,-2.764), nrow=2, byrow=TRUE),
  d=NULL, D=1.0, add_initial=0)
# Figure 1 in Muraki, 1993 (APM)
model_gpcm_plot(a=1, b=matrix(c(0,-2,4,0,-2,2,0,-2,0,0,-2,-2,0,-2,-4), nrow=5, byrow=TRUE),
  d=NULL, D=1.0)
# Figure 2 in Muraki, 1993 (APM)
model_gpcm_plot(a=1, b=matrix(c(0,-2,4,0,-2,2,0,-2,0,0,-2,-2,0,-2,-4), nrow=5, byrow=TRUE),
  d=NULL, D=1.0, type='info', by_item=TRUE)
with(model_gpcm_gendata(5, 50, 3, set_initial=0),
  model_gpcm_plot_loglik(u, a, b, NULL, show_mle=TRUE))
## Not run:
data_tru <- model_gpcm_gendata(1500, 30, 3, set_initial=0)
data_est <- model_gpcm_jmle(data_tru$u, prior=NULL, debug=TRUE)
evaluate_gpcm_estimation(data_tru, data_est)

## End(Not run)

```

mst

Computerized Multistage Testing (MST)

Description

Computerized Multistage Testing (MST)

`mst` creates a multistage (MST) object for assembly

`mst_route` adds/removes a route to/from the MST

`mst_get_indices` maps the input indices to the actual indices

`mst_obj` adds objective functions to the MST

`mst_constraint` adds constraints to the MST

`mst_stage_length` sets length limits on stages

`mst_rdp` anchors the routing decision point (rdp) between adjacent modules

mst_module_mininfo sets the minimum information for modules
 mst_assemble assembles the mst
 mst_get_items extracts items from the assembly results

Usage

```
mst(pool, design, num_panel, method = c("topdown", "bottomup"), len = NULL,
     max_use = NULL, group = NULL, ...)

mst_route(x, route, op = c("+", "-"))

mst_get_indices(x, indices)

mst_obj(x, theta, indices = NULL, target = NULL, flatten = NULL)

mst_constraint(x, coef, min = NA, max = NA, level = NULL,
              indices = NULL)

mst_stage_length(x, stages, min = NA, max = NA)

mst_rdp(x, theta, indices, tol)

mst_module_mininfo(x, theta, mininfo, indices)

mst_assemble(x, ...)

## S3 method for class 'mst'
print(x, ...)

## S3 method for class 'mst'
plot(x, ...)

mst_get_items(x, panel = NULL, stage = NULL, module = NULL,
              route = NULL, route_index = NULL)
```

Arguments

pool	the item pool (data.frame)
design	the MST design (string): e.g., "1-3", "1-2-2", "1-2-3"
num_panel	the number of panels (integer)
method	the design method (string): 'topdown' or 'bottomup'
len	the module/route length (integer)
max_use	the maximum selection of items (integer)
group	the grouping variable (string or vector)
...	further arguments
x	the MST object

route	a MST route represented by a vector of module indices
op	"+" to add a route and "-" to remove a route
indices	the indices of the route (topdown) or the module (bottomup) where objectives are added
theta	a theta point or interval over which the TIF is optimized
target	the target values of the TIF objectives. NULL for maximization
flatten	the parameter for getting a flat TIF
coef	the coefficients of the constraint
min	the lower bound of the constraint
max	the upper bound of the constraint
level	the constrained level, NA for quantitative variable
stages	the stage indices
tol	tolerance parameter (numeric)
mininfo	the minimum information threshold
panel	the panel indices (numeric vector)
stage	the stage indices (numeric vector)
module	the module indices (numeric vector)
route_index	the route indices (integer)

Details

There are two methods for designing a MST. The bottom-up approach adds objectives and constraints on individual modules, whereas the topdown approach adds objectives and constraints directly on routes.

`plot.mst` draws module information functions when `byroute=FALSE` and route information functions when `byroute=TRUE`

Examples

```
## Not run:
## generate item pool
num_item <- 300
pool <- with(model_3pl_gendata(1, num_item), data.frame(a=a, b=b, c=c))
pool$id <- 1:num_item
pool$content <- sample(1:3, num_item, replace=TRUE)
pool$time <- round(rlnorm(num_item, 4, .3))
pool$group <- sort(sample(1:round(num_item/3), num_item, replace=TRUE))

## ex. 1: 1-2-2 MST, 2 panels, topdown
## 20 items in total and 10 items in content area 1 in each route
## maximize info. at -1 and 1 for easy and hard routes
x <- mst(pool, "1-2-2", 2, 'topdown', len=20, max_use=1)
x <- mst_obj(x, theta=-1, indices=1:2)
x <- mst_obj(x, theta=1, indices=3:4)
x <- mst_constraint(x, "content", 10, 10, level=1)
```



```

x <- mst_assemble(x, timeout=5)
plot(x, byroute=TRUE)
for(p in 1:x$num_panel)
  for(r in 1:x$num_route) {
    route <- paste(x$route[r, 1:x$num_stage], collapse='-')
    count <- sum(mst_get_items(x, panel=p, route_index=r)$content==1)
    cat('panel=', p, ', route=', route, ': ', count, ' items in content area #1\n', sep='')
  }

## ex. 2: 1-2-3 MST, 2 panels, bottomup,
## remove two routes with large theta change: 1-2-6, 1-3-4
## 10 items in total and 4 items in content area 2 in each module
## maximize info. at -1, 0 and 1 for easy, medium, and hard modules
x <- mst(pool, "1-2-3", 2, 'bottomup', len=10, max_use=1)
x <- mst_route(x, c(1, 2, 6), "--")
x <- mst_route(x, c(1, 3, 4), "--")
x <- mst_obj(x, theta= 0, indices=c(1, 5))
x <- mst_obj(x, theta=-1, indices=c(2, 4))
x <- mst_obj(x, theta= 1, indices=c(3, 6))
x <- mst_constraint(x, "content", 4, 4, level=2)
x <- mst_assemble(x, timeout=10)
plot(x, byroute=FALSE)
for(p in 1:x$num_panel)
  for(m in 1:x$num_module){
    count <- sum(mst_get_items(x, panel=p, module=m)$content==2)
    cat('panel=', p, ', module=', m, ': ', count, ' items in content area #2\n', sep='')
  }

## ex.3: same with ex.2 (w/o content constraints), but group-based
x <- mst(pool, "1-2-3", 2, 'bottomup', len=12, max_use=1, group="group")
x <- mst_route(x, c(1, 2, 6), "--")
x <- mst_route(x, c(1, 3, 4), "--")
x <- mst_obj(x, theta= 0, indices=c(1, 5))
x <- mst_obj(x, theta=-1, indices=c(2, 4))
x <- mst_obj(x, theta= 1, indices=c(3, 6))
x <- mst_assemble(x, timeout=10)
plot(x, byroute=FALSE)
for(p in 1:x$num_panel)
  for(m in 1:x$num_module){
    items <- mst_get_items(x, panel=p, module=m)
    cat('panel=', p, ', module=', m, ': ', length(unique(items$id)), ' items from ',
        length(unique(items$group)), ' groups\n', sep='')
  }

## ex.4: 2 panels of 1-2-3 top-down design
## 20 total items and 10 items in content area 3
## 6+ items in stage 1 & 2
x <- mst(pool, "1-2-3", 2, "topdown", len=20, max_use=1)
x <- mst_route(x, c(1, 2, 6), "--")
x <- mst_route(x, c(1, 3, 4), "--")
x <- mst_obj(x, theta=-1, indices=1)
x <- mst_obj(x, theta=0, indices=2:3)
x <- mst_obj(x, theta=1, indices=4)

```

```

x <- mst_constraint(x, "content", 10, 10, level=3)
x <- mst_stage_length(x, 1:2, min=6)
x <- mst_assemble(x, timeout=15)
head(x$items)
plot(x, byroute=FALSE)
for(p in 1:x$num_panel)
  for(s in 1:x$num_stage){
    items <- mst_get_items(x, panel=p, stage=s)
    cat('panel=', p, ', stage=', s, ': ', length(unique(items$id)), ' items\n', sep='')
  }

## ex.5: same with ex.4, but use RDP instead of stage length to control routing errors
x <- mst(pool, "1-2-3", 2, "topdown", len=20, max_use=1)
x <- mst_route(x, c(1, 2, 6), "-")
x <- mst_route(x, c(1, 3, 4), "-")
x <- mst_obj(x, theta=-1, indices=1)
x <- mst_obj(x, theta=0, indices=2:3)
x <- mst_obj(x, theta=1, indices=4)
x <- mst_constraint(x, "content", 10, 10, level=3)
x <- mst_rdp(x, 0, 2:3, .1)
x <- mst_module_mininfo(x, 0, 5, 2:3)
x <- mst_assemble(x, timeout=15)
plot(x, byroute=FALSE)

## End(Not run)

```

mst_sim

Simulation of Multistage Testing

Description

Simulation of Multistage Testing
mst_sim simulates a MST administration

Usage

```
mst_sim(x, true, rdp = NULL, ...)
```

```
## S3 method for class 'mst_sim'
print(x, ...)
```

```
## S3 method for class 'mst_sim'
plot(x, ...)
```

Arguments

x	the assembled MST
true	the true theta parameter (numeric)
rdp	routing decision points (list)
...	additional option/control parameters

Examples

```

## Not run:
## assemble a MST
nitems <- 200
pool <- with(model_3pl_gendata(1, nitems), data.frame(a=a, b=b, c=c))
pool$content <- sample(1:3, nrow(pool), replace=TRUE)
x <- mst_obj(pool, "1-2-2", 2, 'topdown', len=20, max_use=1)
x <- mst_obj(x, theta=-1, indices=1)
x <- mst_obj(x, theta=0, indices=2:3)
x <- mst_obj(x, theta=1, indices=4)
x <- mst_constraint(x, "content", 6, 6, level=1)
x <- mst_constraint(x, "content", 6, 6, level=2)
x <- mst_constraint(x, "content", 8, 8, level=3)
x <- mst_stage_length(x, 1:2, min=5)
x <- mst_assemble(x, timeout=3)

## ex. 1: administer the MST using fixed RDP for routing
x_sim <- mst_sim(x, .5, list(stage1=0, stage2=0))
plot(x_sim)

## ex. 2: administer the MST using the max. info. for routing
x_sim <- mst_sim(x, .5)
plot(x_sim, ylim=c(-5, 5))

## End(Not run)

```

utils

*Utility functions***Description**

Utility functions

rmse computes the root mean squared error of two numeric vectors/matrices

freq computes the frequency and percentage of given values

evaluate_3pl_estimation evaluates estimation results against true values

evaluate_gpcm_estimation evaluates estimation results against true values

Usage

rmse(x, y)

freq(x, values = NULL)

hermite_gauss(num_quad = 20)

evaluate_3pl_estimation(data_tru, data_est)

evaluate_gpcm_estimation(data_tru, data_est)

Arguments

x	a vector/matrix of numeric values
y	a vector/matrix of numeric values
values	a vector of valid values, NULL for all values
num_quad	the number of quadrature points
data_tru	a list of true parameters
data_est	a list of estimated parameters

Examples

```
rmse(1 + rnorm(100), 2 + rnorm(100))  
freq(sample(1:5, 100, replace=TRUE))
```

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