

Package ‘AGread’

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Title Read Data Files from ActiGraph Monitors

Version 0.1.2

Description Standardize the process of bringing various modes of output files into R. For more information, see:
<<https://actigraph.desk.com/customer/en/portal/articles/2515800-what-do-the-different-mode-numbers-mean-in-a-csv-or-dat-file->>.
Additionally, processes are provided to read and minimally pre-process raw data from primary accelerometer and inertial measurement unit files. ActiGraph monitors are used to estimate physical activity outcomes via body-worn sensors that measure (e.g.) acceleration or rotational velocity.

Depends R (>= 2.10)

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Imports data.table (>= 1.10.4), utils (>= 3.4.3), stats (>= 3.4.3),
dplyr (>= 0.5.0), seewave (>= 2.0.5), magrittr (>= 1.5),

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URL <https://github.com/paulhibbing/AGread>

BugReports <https://github.com/paulhibbing/AGread/issues>

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AGread

Read Data Files from ActiGraph Monitors

Description

This provides support for reading ActiGraph files of various modes into R. For more information see: <https://actigraph.desk.com/customer/en/portal/articles/2515800-what-do-the-different-mode-numbers-mean>. Additionally, functions are provided to read and minimally pre-process raw data from primary accelerometer and inertial measurement unit files.

Core functions

[read_AG_counts](#)

[read_AG_raw](#)

[read_AG_IMU](#)

Examples

```
read_AG_counts(system.file("extdata", "Example.csv", package = "AGread"), skip = 11)
read_AG_raw(system.file("extdata", "TestID_LeftWrist_RAW.csv", package = "AGread"))
read_AG_IMU(system.file("extdata", "TestID_LeftWrist_IMU.csv", package = "AGread"))
```

AG_collapse	<i>Collapse primary accelerometer data</i>
-------------	--

Description

Collapse primary accelerometer data

Usage

```
AG_collapse(AG, output_window_secs = 1, samp_freq)
```

Arguments

AG	a dataframe of raw primary accelerometer data
output_window_secs	the desired epoch length; defaults to one second
samp_freq	The sampling frequency

Examples

```
data(raw_to_collapse)
AG_collapse(raw_to_collapse, 1, 80)
```

AG_meta	<i>Extract meta-data from file header</i>
---------	---

Description

Extract meta-data from file header

Usage

```
AG_meta(file, verbose = FALSE, ...)
```

Arguments

file	A character scalar giving path to an automatically-generated csv file with count values
verbose	A logical scalar: Print processing updates?
...	Further arguments passed to read.csv and fread

Examples

```
counts_file <- system.file("extdata", "Example.csv", package = "AGread")
AGread::AG_meta(counts_file)
```

check_columns	<i>Check if the primary accelerometer file is formatted correctly</i>
---------------	---

Description

check_columns returns a logical scalar indicating whether there is a formatting issue with the file passed as the argument. A value of TRUE indicates the test has passed, whereas FALSE indicates an issue.

Usage

```
check_columns(file)
```

Arguments

file A character scalar giving path to primary accelerometer file

Examples

```
raw_file <-  
  system.file("extdata",  
             "TestID_LeftWrist_RAW.csv",  
             package = "AGread")  
  
check_columns(raw_file)
```

check_second	<i>Check if the IMU data start on an exact second</i>
--------------	---

Description

Check if the IMU data start on an exact second

Usage

```
check_second(AG)
```

Arguments

AG a dataframe of IMU data

Examples

```
data(imu_to_check)  
check_second(imu_to_check)
```

classify_magnetometer *Convert magnetometer signal to cardinal direction*

Description

Convert magnetometer signal to cardinal direction

Usage

```
classify_magnetometer(x = "Magnetometer X", y = "Magnetometer Y",  
  z = "Magnetometer Z", orientation = "vertical")
```

Arguments

x	x-axis magnetometer data
y	y-axis magnetometer data
z	z-axis magnetometer data
orientation	the conversion scheme to use, from c("vertical", "horizontal")

Value

A vector of cardinal directions assigned from the set N, NNE, NE, ENE, E, ESE, SE, SSE, S, SSW, SW, WSW, W, WNW, NW, NNW, where N, E, S, and W are north, east, south, and west, respectively.

See Also

http://s3.amazonaws.com/actigraphcorp.com/wp-content/uploads/2017/11/26205750/ActiGraph_IMU_White_Paper.pdf

Examples

```
data(imu_to_collapse)  
  
X <- mean(imu_to_collapse$Magnetometer.X)  
Y <- mean(imu_to_collapse$Magnetometer.Y)  
Z <- mean(imu_to_collapse$Magnetometer.Z)  
  
classify_magnetometer(X, Y, Z)
```

get_day_of_year *Julian Date*

Description

A wrapper to retrieve the Julian date.

Usage

```
get_day_of_year(timestamp, format = "%Y-%m-%d %H:%M:%S")
```

Arguments

timestamp A character vector containing timestamp information
format The date-time format of the timestamp vector

Value

A numeric vector of Julian dates.

Examples

```
key_dates <- c("2018-01-01", "2018-12-31")  
  
get_day_of_year(key_dates, "%Y-%m-%d")
```

get_duration *Provide the run time of processing*

Description

Provide the run time of processing

Usage

```
get_duration(timer)
```

Arguments

timer The initial time

Examples

```
timer <- proc.time()  
Sys.sleep(2.2)  
AGread::message_update(16, dur = get_duration(timer))
```

get_imu_file_meta	<i>Get file metadata (sampling frequency, start time, and samples per epoch) for primary accelerometer</i>
-------------------	--

Description

Get file metadata (sampling frequency, start time, and samples per epoch) for primary accelerometer

Usage

```
get_imu_file_meta(file, output_window_secs = 1)
```

Arguments

file	character scalar giving path to IMU file
output_window_secs	the desired epoch length, over which to average IMU data

Examples

```
imu_file <-  
  system.file("extdata",  
    "TestID_LeftWrist_IMU.csv",  
    package = "AGread")  
  
get_imu_file_meta(imu_file)
```

get_minute	<i>Numerical Minute of the Day.</i>
------------	-------------------------------------

Description

Converts a timestamp to a numerical value between 0 (midnight) and 1439 (23:59). Seconds can be represented using a rational decimal.

Usage

```
get_minute(timestamp, format = "%Y-%m-%d %H:%M:%S", rational = FALSE)
```

Arguments

timestamp	A character vector containing timestamp information
format	The date-time format of the timestamp vector
rational	A logical scalar. Use rational number to represent seconds?

Examples

```
key_times <-  
  paste("2018-03-15",  
        c("00:00:00",  
          "01:00:00",  
          "12:00:00",  
          "23:59:59"))  
  
get_minute(key_times)  
get_minute(key_times, rational = TRUE)
```

get_raw_file_meta	<i>Get file metadata (sampling frequency and timestamps) for primary accelerometer</i>
-------------------	--

Description

Get file metadata (sampling frequency and timestamps) for primary accelerometer

Usage

```
get_raw_file_meta(file)
```

Arguments

file character scalar giving path to primary accelerometer file

Examples

```
raw_file <-  
  system.file("extdata",  
             "TestID_LeftWrist_RAW.csv",  
             package = "AGread")  
  
get_raw_file_meta(raw_file)
```

get_VM	<i>Calculate vector magnitude</i>
--------	-----------------------------------

Description

Calculate vector magnitude

Usage

```
get_VM(triaxial, verbose = FALSE)
```

Arguments

triaxial	a dataframe of triaxial data on which to calculate vector magnitude
verbose	print information about variable search criteria?

Value

a vector of vector magnitude values

Examples

```
data(imu_to_collapse)

vm_columns <-
  grepl("accelerometer",
        names(imu_to_collapse),
        ignore.case = TRUE)

get_VM(data.frame(imu_to_collapse)[, vm_columns])
```

imu_collapse	<i>Collapse raw IMU data to a specified epoch</i>
--------------	---

Description

Collapse raw IMU data to a specified epoch

Usage

```
imu_collapse(AG, block_size, verbose = FALSE)
```

Arguments

AG	dataframe containing raw IMU data
block_size	number of samples per epoch
verbose	A logical scalar: Print processing updates?

Value

dataframe of IMU data averaged over the specified epoch length

Examples

```
data(imu_to_collapse)
imu_collapse(imu_to_collapse, 100)
```

imu_filter_gyroscope *Low-Pass filter Gyroscope data*

Description

Low-Pass filter Gyroscope data

Usage

```
imu_filter_gyroscope(AG, samp_rate, filter_hz = 35, verbose = FALSE)
```

Arguments

AG	a dataframe of IMU data
samp_rate	The sampling rate, in Hz
filter_hz	The cutoff for the low-pass filter
verbose	A logical scalar: Print processing updates?

Examples

```
data(imu_to_collapse)
imu_filter_gyroscope(imu_to_collapse, 100)
```

imu_to_check	<i>IMU data to check</i>
--------------	--------------------------

Description

A dataset for demonstrating checks that are applied to IMU data.

Usage

imu_to_check

Format

A data frame with 300 rows and 8 variables:

file_source_IMU The filename of the IMU file

date_processed_IMU The date the IMU file was processed

Timestamp The corresponding time for each row of data

Gyroscope_VM_DegPerS Gyroscope vector magnitude, in degrees per second

mean_abs_Gyroscope_x_DegPerS Rotation in x axis, degrees per second

mean_abs_Gyroscope_y_DegPerS Rotation in y axis, degrees per second

mean_abs_Gyroscope_z_DegPerS Rotation in z axis, degrees per second

mean_magnetometer_direction Cardinal direction of magnetometer signal, averaged over one second

imu_to_collapse	<i>IMU data to collapse</i>
-----------------	-----------------------------

Description

A partially-processed IMU dataset ready to be collapsed from raw samples to one-second summaries.

Usage

imu_to_collapse

Format

A data frame with 1500 rows and 17 variables:

Timestamp The corresponding time for each row of data

Accelerometer.X Secondary accelerometer x-axis data, in G

Accelerometer.Y Secondary accelerometer y-axis data, in G

Accelerometer.Z Secondary accelerometer z-axis data, in G

Temperature Temperature of the IMU, in Celsius

Gyroscope.X Gyroscope x-axis data, in degrees per second

Gyroscope.Y Gyroscope y-axis data, in degrees per second

Gyroscope.Z Gyroscope z-axis data, in degrees per second

Magnetometer.X Magnetometer x-axis data, in micro-Teslas

Magnetometer.Y Magnetometer y-axis data, in micro-Teslas

Magnetometer.Z Magnetometer z-axis data, in micro-Teslas

file_source_IMU The filename of the IMU file

date_processed_IMU The date the IMU file was processed

ms The millisecond value of the timestamp

mean_Accel_VM Vector magnitude of the secondary accelerometer signal, in G

Gyroscope_VM_DegPerS Gyroscope vector magnitude, in degrees per second

Magnetometer_VM_MicroT Vector magnitude of the magnetometer signal, in micro-Teslas

raw_to_collapse

Primary accelerometer data to collapse

Description

A partially-processed primary accelerometer dataset ready to be collapsed from raw samples to one-second summaries.

Usage

raw_to_collapse

Format

A data frame with 24000 rows and 3 variables:

Accelerometer X Primary accelerometer x-axis data, in G

Accelerometer Y Primary accelerometer y-axis data, in G

Accelerometer Z Primary accelerometer z-axis data, in G

read_AG_counts	<i>Read data table files containing count values</i>
----------------	--

Description

Read data table files containing count values

Usage

```
read_AG_counts(file, verbose = FALSE, skip = 10, nrows = 10,
  header = FALSE, ...)
```

Arguments

file	A character scalar giving path to an automatically-generated csv file with count values
verbose	A logical scalar: Print processing updates?
skip	Header length: Number of rows to skip when reading the file
nrows	Header length: Number of rows to read when retrieving meta-data
header	A logical scalar: Are variable names contained in first row of file?
...	Further arguments passed to read.csv and fread

Value

A data frame reflecting the data contained in the csv file

Examples

```
read_AG_counts(system.file("extdata", "Example.csv", package = "AGread"), skip = 11)
```

read_AG_IMU	<i>File reading function for IMU files</i>
-------------	--

Description

File reading function for IMU files

Usage

```
read_AG_IMU(file, output_window_secs = 1, verbose = FALSE, skip = 10,
  filter = TRUE, filter_hz = 35)
```

Arguments

file	character scalar giving the path to the IMU file
output_window_secs	the desired epoch length; defaults to one second
verbose	A logical scalar: Print processing updates?
skip	Header length: Number of rows to skip when reading the file
filter	a logical scalar: Apply a low-pass filter to gyroscope data?
filter_hz	The cutoff for the low-pass filter

Value

A dataframe giving processed IMU data in the specified epoch length

Examples

```
imu_file <-
  system.file("extdata",
             "TestID_LeftWrist_IMU.csv",
             package = "AGread")

read_AG_IMU(imu_file)
```

read_AG_raw *File reading function for primary accelerometer files*

Description

File reading function for primary accelerometer files

Usage

```
read_AG_raw(file, output_window_secs = 1, verbose = FALSE, skip = 10)
```

Arguments

file	A character scalar giving path to primary accelerometer file
output_window_secs	the desired epoch length; defaults to one second
verbose	A logical scalar: Print processing updates?
skip	Header length: Number of rows to skip when reading the file

Value

A dataframe giving processed raw data from the primary accelerometer in the specified epoch length

Examples

```
raw_file <-  
  system.file("extdata",  
    "TestID_LeftWrist_RAW.csv",  
    package = "AGread")  
  
read_AG_raw(raw_file)
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